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Djidere Ahmadou

Universite de Ngaoundere

Alphonse Houwe

Universite de Maroua

Justin Mibaile

Universite de Maroua

Gambo Betchewe

Universite de Maroua

Serge Y. Doka

Universite de Ngaoundere

Kofane T. Crepin

University of Yaounde I: Universite de Yaounde I

Mustafa Inc (✉ minc@firat.edu.tr)

Firat Universitesi <https://orcid.org/0000-0003-4996-8373>

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Solitary waves and modulation instability with the influence of fractional derivative order in nonlinear left-handed transmission line

Djidere Ahmadou^{a,*}, Houwe Alphonse^b, Mibaile Justin^c, Gambo Betchewe^b,
Doka Yamigno Serge^a, Kofane Timoleon Crepin^d, Mustafa Inc^{e,f}

^a*Department of Physics, Faculty of Science, The University of Ngaoundere, P.O. Box 454, Ngaoundere, Cameroon*

^b*Department of Physics, Faculty of Science, The University of Maroua, P.O. Box 814, Cameroon*

^c*Higher Teachers' Training College of Maroua, The University of Maroua, P.O. Box. 46, Maroua, Cameroon*

^d*Department of Physics, Faculty of Science, The University of Yaounde I, P.O. Box 812, Yaounde, Cameroon*

^e*Department of Mathematics, Firat University, 23119 Elazig, Turkey*

^f*Department of Medical Research, China Medical University Hospital, China Medical University, Taichung, Taiwan*

Abstract

The resolution of the reduced fractional nonlinear Schrödinger equation obtained from the model describing the wave propagation in the left-handed nonlinear transmission line presented by Djidere et al recently, allowed us in this work through the Adomian decomposition method (ADM) to highlight the behavior and to study the propagation process of the dark and bright soliton solutions with the effect of the fractional derivative order as well as the Modulation Instability gain spectrum (MI) in the LHNLTTL. By inserting fractional derivatives in the sense of Caputo, we used ADM to structure the approximate solitons solutions of the fractional nonlinear Schrödinger equation reduced with fractional derivatives. The pipe is obtained from the bright and dark soliton by the fractional derivatives order (see Figures 2 and 5). By the bias of MI gain spectrum the instability zones occur when the value of the fractional derivative order tends to 1. Furthermore, when the fractional derivative order takes small

*Corresponding author.

Email address: djidereahmadou@gmail.com, minc@firat.edu.tr (Djidere Ahmadou)

values, stability zones appear. These results could bring new perspectives in the study of solitary waves in left-handed metamaterials, as the memory effect could have a better future for the propagation of modulated waves because we also show in this article that the stabilization of zones of the dark and bright solitons could be described by a fractional nonlinear Schrödinger equation with small values of fractional derivatives order. In addition, the obtained significant results are new and could find applications in many research areas such as in the field of information and communication technologies.

Keywords: Solitary waves, modulation instability, fractional derivative order, nonlinear left-handed transmission line

1. Introduction

The evolution of digital electronics and communication has made enormous advances, particularly in the transmission of information. In previous years, coaxial cables were mainly used, which transported signals with a lot of losses. To overcome this difficulty, researchers have introduced a recent class of materials, called "metamaterials", to simplify the size of components and thus reduce maximum losses by making them more efficient. As a result, the micro line ribbons [1] were born. The expression "metamaterial" was first mentioned in the field of optics by the Russian physicist [2] when he theoretically introduced the concept of left-handed materials and its realization by [3].

In this current work, we focus on the study of the propagation of dark and bright solitons in the left-handed nonlinear transmission line (LHNLTL) by the Adomian decomposition method with the effect of the fractional derivative order (α). Recently in literature fractional differential equations have been of great interest. Nowadays, there has been considerable attention in non linear evolution equations having fractional differential equations. At the very beginning, there were hardly any practical applications of fractional calculus, and it was highly regarded as an obscure field with only rarely or not at all advantageous mathematical manipulations. For almost 30 years, the paradigm began to move

20 from simple mathematical formulations to applications in several fields. For
 previous years, fractional calculus was used and applied to almost all areas of
 science, engineering and mathematics. Fields of application of fractional dif-
 ferentiation and fractional integration are already well established, others have
 just begun and will continue. Fractional computation applications are found
 25 in turbulence and fluid dynamics, stochastic dynamical system, plasma physics
 and controlled thermonuclear fusion, nonlinear control theory, image processing,
 nonlinear biological systems, astrophysics [4, 5], [6, 7],[8, 9],[10, 11, 12], [13, 14].
 Nevertheless, some historical summaries of the developments of the fractional
 calculation developments used can be found in the works of [4, 5] and [6]. Several
 30 methods to obtain exact solutions or even soliton solutions to nonlinear partial
 differential equations have been proposed, such as the Bäcklund transformation
 method [15], the Hirota's bilinear method [16], the inverse scattering transform
 method [17], the extended tanh method [18], the Adomian approximation [19],
 the variational method [20], the variational iteration method [21], the various
 35 Lindstedt-Poincare methods [22], the Adomian decomposition method (ADM)
 [23, 24, 25, 26, 27], the F-expansion method [28], the exp-function method [29],
 the homotopy perturbation method [30, 31] and the results on the acquired
 solitary waves were successful thanks to the different mathematical methods re-
 cently used such as the Darboux transformation [32, 33, 34, 35], Hirota-Riemann
 40 method [36], numerical simulation [37], Hirota method [38].

The main purpose of this work is to investigate the behavior of the dark and
 bright solitons by a nonlinear evolution equation with fractional order describing
 the waves propagation in nonlinear left-handed electrical transmission line giving
 by [39, 40],

$$\frac{\partial U}{\partial z} - \beta_2 \frac{j^{-3\alpha}}{(2\alpha)!} \frac{\partial^{2\alpha} U}{\partial t^{2\alpha}} - (j + j^{-\alpha})\beta_0 U + T_4 |U|^2 U = 0. \quad (1)$$

45 Thus, in this article we apply the Adomian decomposition method (ADM)
 to this equation (1) of [39, 40] to study the solutions of dark and bright solitons
 with the effect of fractional derivatives order and initial conditions. The details

of the set of nonlinear evolution equations are specified [39, 40]. Here (α) is the fractional derivative order and $0 < \alpha \leq 1$. The first step will give the overview
50 of the fractional derivative order. The next section will give the preliminaries and the description of the Adomian decomposition method (ADM). Later the behavior of the bright and dark solitons with the effect of derivative order will be examined. Some graphical representation will follow to highlight physical phenomena of the nonlinear left-handed transmission line. The last section will
55 conclude the work.

1.1. Overview of the fractional derivative order

In recent years, several properties aimed at facilitating the use of the fractional derivative have been the subject of various scientific publications, followed by concordant results. It should be remembered that some of the usual properties
60 have not known exclusive salvation. Among the current properties, here are few that will promote the use of the system to be learned with the appropriate derivatives of the order (α) [41, 26, 27] below

$$\frac{d^\alpha k(t)}{dt^\alpha} = \lim_{\epsilon \rightarrow +\infty} \frac{k(t + \epsilon t^{1-\alpha}) - k(t)}{\epsilon}, \quad k : (0, \infty) \rightarrow R. \quad (2)$$

With $t > 0$, $\alpha \in (0, 1]$.

Then if k is α -differentiable in some $(0, c)$, $c > 0$ and $\lim_{t \rightarrow 0^+} D^\alpha(k)(t)$ exists,
65 however by accuracy

- $D^\alpha(g)(0) = \lim_{t \rightarrow 0^+} D^\alpha(k)(t).$

Taking into account [42, 43, 26, 27], the following relevant properties of fractional derivatives are presented as follows:

- $D_t^\alpha(cg + ek) = cD_t^\alpha g + eD_t^\alpha k, \quad \text{and} \quad c, e \in R.$
- 70 • $D_t^\alpha(t^\mu) = \mu t^{\mu-\alpha} \quad \text{and} \quad \mu \in R.$
- $D_t^\alpha(gk) = kD_t^\alpha(g) + fD_t^\alpha(k) .$

- $D_t^\alpha \left(\frac{g}{k} \right) = \frac{k D_t^\alpha(g) - g D_t^\alpha(k)}{g^2}.$
- So if g is differentiable, $D_t^\alpha(g)(t) = t^{1-\alpha} \frac{dg}{dt}.$
- if $g, k: (0, \infty) \rightarrow R$ is differentiable and α the differentiable functions:
 $D_t^\alpha(gok)(t) = t^{1-\alpha} k'(t) g'(k(t)).$

75

2. Preliminaries and Adomian decomposition method (ADM)

2.1. Preliminaries

Considering equation (1), we can obtain the following nonlinear Schrödinger equation with nonlocal operator of Riemann-Liouville as follows

$$\beta_2 \frac{j^{-3\alpha}}{(2\alpha)!} \text{ID}_t^{2\alpha} U - \frac{\partial U}{\partial z} + (j + j^{-\alpha}) \beta_0 U - T_4 |U|^2 U = 0, \quad (3)$$

80 with respectively $\beta_0 = 1/(\omega_0^\alpha \sqrt{L_L C_0})$ the phase velocity, $\beta_2 = 2/(\omega_0^{3\alpha} \sqrt{L_L C_L})$ the second order dispersion constant and $T_4 = \rho^2/4(\omega_0 \sqrt{L_L C_0})^3$ the Kerr nonlinear part of the left-handed nonlinear transmission line (LHNLTL), where (ρ) is a constant of the polarization, and $0 < \alpha \leq 1$ [39], while the nonlocal operator $\text{ID}_t^{2\alpha}$ in the sence of Riemann-Liouville read as

$$\text{ID}_t^\sigma U(z, t) = \frac{1}{\Gamma(2-\sigma)} \frac{d^2}{dt^2} \int_0^t (t-s)^{1-\sigma} \left[U(z, s) - U(z, 0) - s \frac{d}{ds} U(z, 0) \right] ds. \quad (4)$$

85 For simplification purpose, we set: $A = \beta_2 \frac{j^{-3\alpha}}{(2\alpha)!}$, $B = (j + j^{-\alpha}) \beta_0$, $\sigma = 2\alpha$, so that equation (3) becomes

$$A \text{ID}_t^\sigma U - \partial_z U + BU - T_4 |U|^2 U = 0, \quad U(z, 0) = f(z), \quad j = \sqrt{-1}. \quad (5)$$

This part can be found in several chapters of physics, especially plasma physics, nonlinear optics, superconductivity, etc. However, cubic nonlinearity is the most common nonlinearity in applications. Nevertheless, this is a simplified
 90 model for examining Bose-Einstein condensates, Kerr medium and nonlinear optical anomalous waves in the ocean [44, 45, 46, 47, 48, 49].

Thus, [44] studied a nonlinear Schrödinger equation such as the equation (1) of [39] by applying the differential transformation method to obtain its approximate solution.

95 Let's consider equation (1) in this work and we grant several definitions and basic properties of the theory of fractional calculus that are further applied in these papers [5, 6]. Using fractional calculus in the sense of Riemann-Liouville and then the Adomian decomposition method with the effect of the fractional derivative order, and we get this fractional nonlinear Schrödinger equation of
100 the form equation (3) then equation (4).

For the purpose of simplification, equation (3) can be reduced to equation (5). It is worthwhile mentioning that equation (5) is a complex differential equation, with complex modulus term $|U|^2$, which is nonlinear. Therefore an appropriate method to sort-out solution of equation (5) is needed. We shall use
105 in the following the Adomian decomposition method.

2.2. Adomian decomposition method (ADM)

The Adomian decomposition method is an iteration method for solving linear, nonlinear, algebraic equations. The main advantage of this ADM is to provide solutions of an infinite series, which converges quickly to the solution
110 exact. The ADM consists in dividing a given equation into linear and nonlinear parts, inverting the higher-order derivative operator.

2.2.1. Description of the Adomian decomposition method

Consider a general nonlinear equation in canonical form as

$$\mathcal{L}U + VU + WU = 0, \quad (6)$$

where the linear part of a general nonlinear equation (6) is $\mathcal{L}(U) + V(U)$.
115 $\mathcal{L}(U)$ is a linear operator easily invertible, $V(U)$ is the part equation and the nonlinear term is represented by $W(U)$.

The technique consists of decomposition the linear and nonlinear parts of equation (6) to apply linear operator of the highest-ordered derivation of terms.

Notice here, \mathcal{L} is a linear operator given as $\mathcal{L} = \frac{d}{dt}(\cdot)$. Its inverse \mathcal{L}^{-1} is defined
 120 as $\mathcal{L}^{-1} = \int_0^t (\cdot) ds$.

If we apply inverse operator \mathcal{L}^{-1} in all sided of equation (6) and using the initial condition $U(z, 0) = f(z)$, we get the following equivalent equation

$$\mathcal{L}^{-1} \mathcal{L}(U) = -\mathcal{L}^{-1} V(U) - \mathcal{L}^{-1} W(U), \quad (7)$$

this $\mathcal{L}^{-1} \mathcal{L}(U) = U(z, t) - U(z, 0)$.

Next we shall write the linear terms broken up by an infinite series compo-
 125 nents of the functions $U(z, t)$ defined as

$$U(z, t) = \sum_{n=0}^{\infty} U_n(z, t), \quad (8)$$

the nonlinear term $W(U)$ can be decomposed into an infinite series of polynomials

$$W(U) = \sum_{n=0}^{\infty} A_n, \quad (9)$$

where A_n is called Adomian Polynomial of $U_n(z, t)$. Substituting equation (8) and equation (9) into equation (6) we have

$$\sum_{n=0}^{\infty} U_n = U_0(z, 0) - \mathcal{L}^{-1} V \sum_{n=0}^{\infty} U_n - \mathcal{L}^{-1} \sum_{n=0}^{\infty} A_n, \quad (10)$$

$$\begin{cases} U_0(z, 0) &= f(z), \\ U_{n+1}(z, t) &= -\mathcal{L}^{-1} V U_n - \mathcal{L}^{-1} A_n. \end{cases} \quad (11)$$

130 We compute the elements of $U_n(z, t)$, $n = 0, 1, 2, \dots$, using recursive relations:

$$U_1 = -\mathcal{L}^{-1} V U_0 - \mathcal{L}^{-1} A_0, \quad (12)$$

$$U_2 = -\mathcal{L}^{-1} V U_1 - \mathcal{L}^{-1} A_1, \quad (13)$$

$$U_{n+1} = -\mathcal{L}^{-1} V U_n - \mathcal{L}^{-1} A_n. \quad (14)$$

It consist to:

135

- Show the initial condition as the first term of the solution in infinite solutions of series;
- Break down the nonlinear function, in terms of special, polynomials which is called Adomian's polynomials;
- 140 • Provide successive terms of series solution by recurrence using Adomian's polynomials as

$$A_n(U_0, U_1, U_2, \dots, U_n) = \frac{1}{n!} \left\{ \frac{d^n}{d\lambda^n} \left[\left(\sum_{k=0}^n \lambda^k U_k \right) \left(\sum_{k=0}^n \lambda^k U_k^* \right) \left(\sum_{k=0}^n \lambda^k U_k \right) \right]_{\lambda=0} \right\}. \quad (15)$$

3. Dark and Bright solitons solutions

In this section it is assumed the following dark and bright expression as solutions of equation (5):

$$\begin{cases} U(z, t) = \tanh(kz - \omega t) e^{j(z-vt)}, \\ U(z, t) = D \operatorname{sech}(kz - \omega t) e^{j(z-vt)}. \end{cases} \quad (16)$$

145 Here D is a constant to be determined later. At the initial condition ($t = 0, U_0 = \tanh(kz) e^{jz}, U_0 = D \operatorname{sech}(kz) e^{jz}$).

The next section will emphasize the behavior of the dark and bright soliton solutions by employing the Adomian decomposition method.

3.1. Application of the Adomian decomposition method

150 3.1.1. Fractional dark soliton solutions

We now consider equation (5) which is a fractional nonlinear Schrödinger equation. Applying the fractional Riemann-Liouville integral of order σ to equation (5) we get:

$$I_t^\sigma \left[A \text{ID}_t^\sigma U - \partial_z U + BU - T_4 |U|^2 U \right] = 0, \quad (17)$$

i.e,

$$I_t^\sigma (\text{ID}_t^\sigma U) = \frac{1}{A} I_t^\sigma \left[\partial_z U - BU + T_4 |U|^2 U \right]. \quad (18)$$

155 Now, taking into account the properties of the inverse of the fractional derivative in the sense of Riemann-Liouville, we obtain

$$(I_t^\sigma \text{ID}_t^\sigma U)(t) = U(z, t) - U(z, 0) - t \frac{\partial U(z, 0)}{\partial t}, \quad (19)$$

setting $U(z, 0) = \tanh(kz)e^{jz} = U_0(z)$ and $\frac{\partial U(z, 0)}{\partial t} = 0$, we get:

$$U(z, t) = U(z, 0) + \frac{1}{A} I_t^\sigma \left[\partial_z U - BU + T_4 |U|^2 U \right]. \quad (20)$$

Using the ADM on equation (20), we divide the given equation into linear and nonlinear parts, the higher-order derivative operator contained in the linear operator on both sides and show the initial conditions and the first term of the series solution, it is obtained :

$$\begin{cases} U_0(z, 0) &= \tanh(kz)e^{jz}, \\ U_{n+1}(z, t) &= \frac{1}{A} I_t^\sigma [\partial_z U_n - BU_n + T_4 A_n], n \geq 0. \end{cases} \quad (21)$$

Where $A_n = |U|^2 U$ and $U(z, 0) = f(z)$. As in the Adomian decomposition method [23, 24, 25, 50], if we consider that a serial solution of the function $U(z, t)$ is provided by equation (8) and the nonlinear term A_n can be dissociated into an infinite range of polynomials yielded by equation (9). However, components $U_n(z, t)$ will be calculated recursively, the A_n are considered as the adomial polynomials of the U_n .

Some exclusive algorithms have been determined in [23, 24, 25, 51, 50] to compute the adomial polynomials of the nonlinear terms of equation (15).

170 So, we have

$$U_{n+1}(z, t) = \frac{1}{A} I_t^\sigma [\partial_z U_n - BU_n + T_4 A_n], n \geq 0. \quad (22)$$

Equation (15) leads to :

$$A_0(U_0) = U_0 |U_0|^2,$$

$$A_1(U_0, U_1) = 2U_1 |U_0|^2 + U_1^* U_0^2,$$

$$A_2(U_0, U_1, U_2) = 2U_2 |U_0|^2 + 2|U_1|^2 U_0 + U_2^* U_0^2 + U_1^2 U_0^*,$$

$$A_3(U_0, U_1, U_2, U_3) = 2U_3 |U_0|^2 + 2U_2 U_1^* U_0 + 2U_2 U_0^* U_1 + 2U_1 U_2^* U_0 + U_1 |U_1|^2 + U_0^2 U_3^*,$$

...

and so forth.

With the application of the above recursive relations in equation (22), and using [4, 5, 25, 51, 27] equation (21).

We structure the approximate solutions of $U(z, t)$ as below:

$$U_1(z, t) = C_1 e^{jz} \frac{t^\sigma}{A\Gamma(\sigma + 1)}, \quad (23)$$

with $C_1 = k \operatorname{sech}^2(kz) + (j - B) \tanh(kz) + T_4 \tanh^3(kz)$,

$$U_2(z, t) = C_2 e^{jz} \frac{t^{2\sigma}}{A^2\Gamma(2\sigma + 1)}, \quad (24)$$

...and so forth.

With $C_2 = 2(j - B)k \operatorname{sech}^2(kz) + (j - B)^2 \tanh(kz) + (j - B)T_4 \tanh^2(kz) + (j - 2B)T_4 \tanh^3(kz) + 3T_4^2 \tanh^5(kz) + (2kT_4 - 2k^2) \tanh(kz) \operatorname{sech}^2(kz) + 3kT_4 \tanh^2(kz) \operatorname{sech}^2(kz)$.

The approximate solution for the fractional nonlinear Schrödinger equation from equation (5) is obtained by adding all solutions obtained above equation (23), equation (24), and then adding the expression of the initial condition $U_0 = \tanh(kz) e^{jz}$ of the dark soliton, we obtain

$$U_{app}(z, t) = U_0 + U_1 + U_2 + \dots$$

$$= \tanh(kz) e^{jz} + C_1 e^{jz} \frac{t^\sigma}{A\Gamma(\sigma+1)} + C_2 e^{jz} \frac{t^{2\sigma}}{A^2\Gamma(2\sigma+1)} + \dots$$

$$U_{app}(z, t) = e^{jz} \left\{ \tanh(kz) + \frac{C_1 t^\sigma}{A\Gamma(\sigma + 1)} + \frac{C_2 t^{2\sigma}}{A^2\Gamma(2\sigma + 1)} + \dots \right\}, \quad (25)$$

and the exact solution $U_{exact}(z, t)$ is obtained when $\alpha \rightarrow 1$ in equation (25), which means that $\sigma \rightarrow 2$ because $\sigma = 2\alpha$.

195 3.1.2. Fractional bright soliton solutions

In this subsection, we proceed in the same way as in the previous subsection to point out the behavior of the bright soliton with the effect of the fractional derivative order by Adomian decomposition method. Following the same way in the subsection given the dark soliton above with the same initial
200 condition.

To this end, we structure the approximate solutions of $U(z, t)$ as below:

$$U_1(z, t) = C_1 e^{jz} \frac{t^\sigma}{A\Gamma(\sigma + 1)}, \quad (26)$$

with $C_1 = (j - B)D\text{sech}(kz) + T_4 D^3 \text{sech}^3(kz) - Dk \tanh(kz) \text{sech}(kz)$,

$$U_2(z, t) = C_2 e^{jz} \frac{t^{2\sigma}}{A^2\Gamma(2\sigma + 1)}, \quad (27)$$

...and so forth.

With $C_2 = (j - B)^2 D \text{sech}(kz) + (T_4 D^3 (2j - 3B) - Dk^2) \text{sech}^3(kz) +$
205 $3T_4 D^5 \text{sech}^5(kz) + 2(B - j) Dk \tanh(kz) \text{sech}(kz) - 6T_4 D^3 k \tanh(kz) \text{sech}^3(kz) +$
 $Dk^2 \tanh^2(kz) \text{sech}(kz)$.

The approximate solution of the Schrödinger fractional nonlinear equation of the equation (5) is obtained by adding all the solutions obtained above the equation (26), the equation (27) and then adding the expression of the initial
210 condition $U_0 = D \text{sech}(kz) e^{jz}$ of the bright soliton, we obtain

$$\begin{aligned} U_{app}(z, t) &= U_0 + U_1 + U_2 + \dots \\ &= D \text{sech}(kz) e^{jz} + C_1 e^{jz} \frac{t^\sigma}{A\Gamma(\sigma + 1)} + C_2 e^{jz} \frac{t^{2\sigma}}{A^2\Gamma(2\sigma + 1)} + \dots \end{aligned}$$

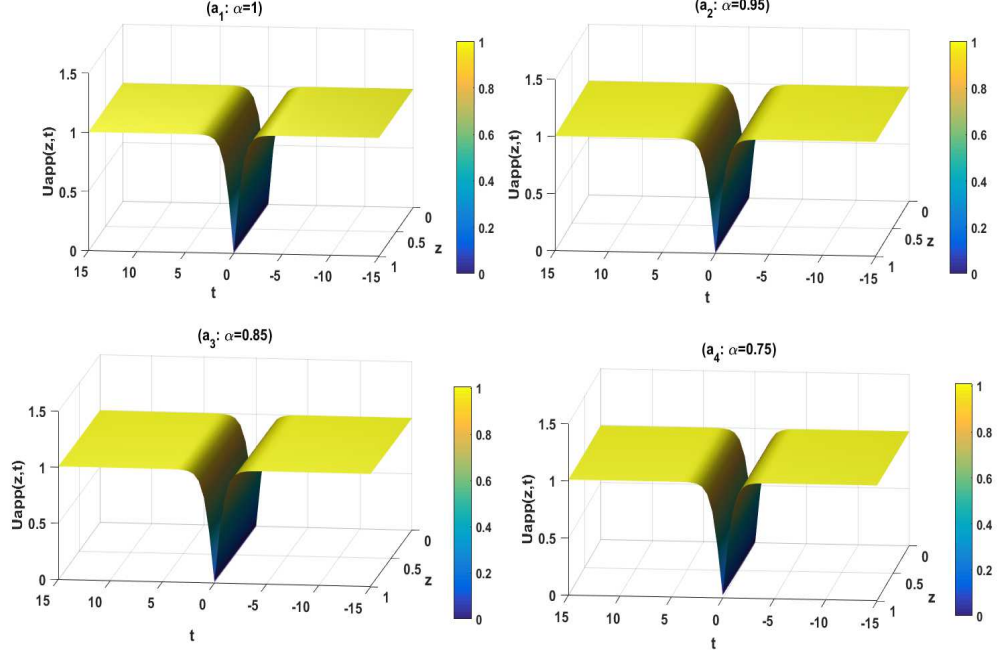


Figure 1: The approximate dark soliton solution obtained by Adomian decomposition method of the equation (25) when $(\alpha = 1, \alpha = 0.95, \alpha = 0.85, \alpha = 0.75)$, $\omega_0 = 0.032 \text{ rad.s}^{-1}$, $C_0 = 100.045 \text{ pH}$, $C_L = 78.65 \text{ pH}$, $L_L = 200.054 \text{ nH}$, $\rho = 0.01$, $k = 0.98$.

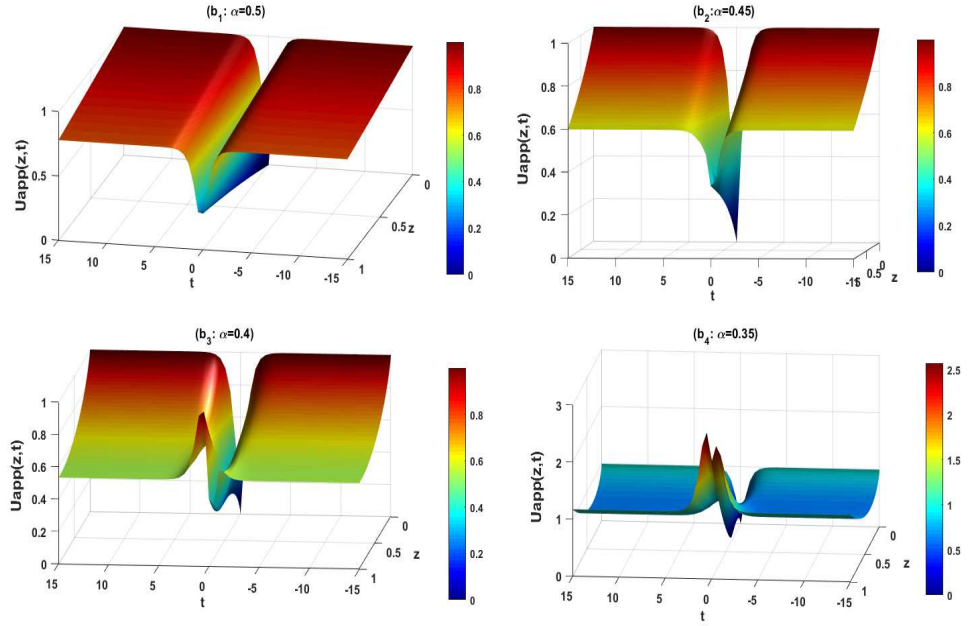


Figure 2: The approximate dark soliton solution obtained by Adomian decomposition method of the equation (25) when $(\alpha = 0.5, \alpha = 0.45, \alpha = 0.4, \alpha = 0.35)$, $\omega_0 = 0.032 \text{ rad.s}^{-1}$, $C_0 = 100.045 \text{ pH}$, $C_L = 78.65 \text{ pH}$, $L_L = 200.054 \text{ nH}$, $\rho = 0.01$, $k = 0.98$.

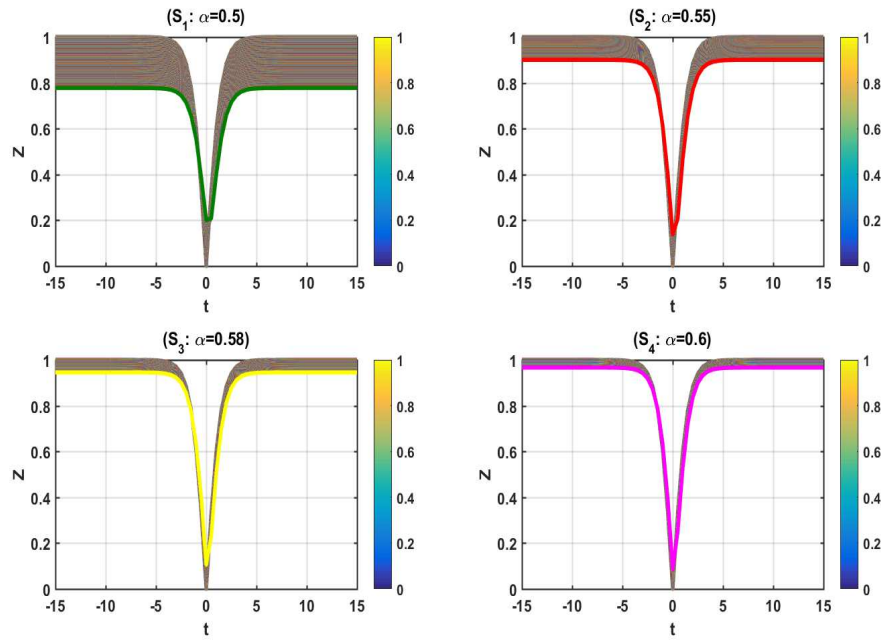


Figure 3: The approximate dark soliton solution obtained by Adomian decomposition method of the equation (25) when $(\alpha = 0.5, \alpha = 0.55, \alpha = 0.58, \alpha = 0.6)$, $\omega_0 = 0.032 \text{ rad.s}^{-1}$, $C_0 = 100.045 \text{ pH}$, $C_L = 78.65 \text{ pH}$, $L_L = 200.054 \text{ nH}$, $\rho = 0.01$, $k = 0.7$.

$$U_{app}(z, t) = e^{jz} \left\{ Dsech(kz) + \frac{C_1 t^\sigma}{A\Gamma(\sigma+1)} + \frac{C_2 t^{2\sigma}}{A^2\Gamma(2\sigma+1)} + \dots \right\}, \quad (28)$$

and the exact solution $U_{exact}(z, t)$ is obtained when $\alpha \rightarrow 1$ in equation (28), which means that $\sigma \rightarrow 2$ because $\sigma = 2\alpha$.

215 3.2. Modulation instability gain

The modulation instability (MI) is the one important phenomenon which happens when the nonlinear and dispersion terms are present in a nonlinear evolution equation. Usually modulation instability is present in a nonlinear system because of the low perturbations enforce on the continuous wave. Now, we
220 consider the steady-state solution of equation (1) as follows

$$U(z, t) = \sqrt{P} e^{jT_4 P z}, \quad (29)$$

where P is the power incident. Suppose the perturb solution of equation (1) in the following expression

$$U(z, t) = (\sqrt{P} + \varepsilon(z, t)) e^{jT_4 P z}. \quad (30)$$

Taking in to account the impact of the perturb field, we obtain the linearized equation

$$\frac{\partial \varepsilon(z, t)}{\partial z} - \beta_2 \frac{j^{-3\alpha}}{(2\alpha)!} \frac{\partial^{2\alpha} \varepsilon(z, t)}{\partial t^{2\alpha}} - 2\beta_2 \frac{j^{-2\alpha}}{(2\alpha)!} \frac{\partial^\alpha \varepsilon(z, t)}{\partial t^\alpha} + T_4 P (\varepsilon(z, t) + \varepsilon^*(z, t)) = 0. \quad (31)$$

225 Where $\varepsilon^*(z, t)$ is the complex conjugate of $\varepsilon(z, t)$. Now we suppose the solution for the perturbed expression as follows

$$\varepsilon(z, t) = a_1 e^{j(Kz + \Omega t)} + a_2 e^{-j(Kz + \Omega t)}, \quad (32)$$

where a_1 and a_2 are reals, while K and Ω are the wave number and modulation frequency, respectively. Let's now introduce equation (32) into equation (31) gives

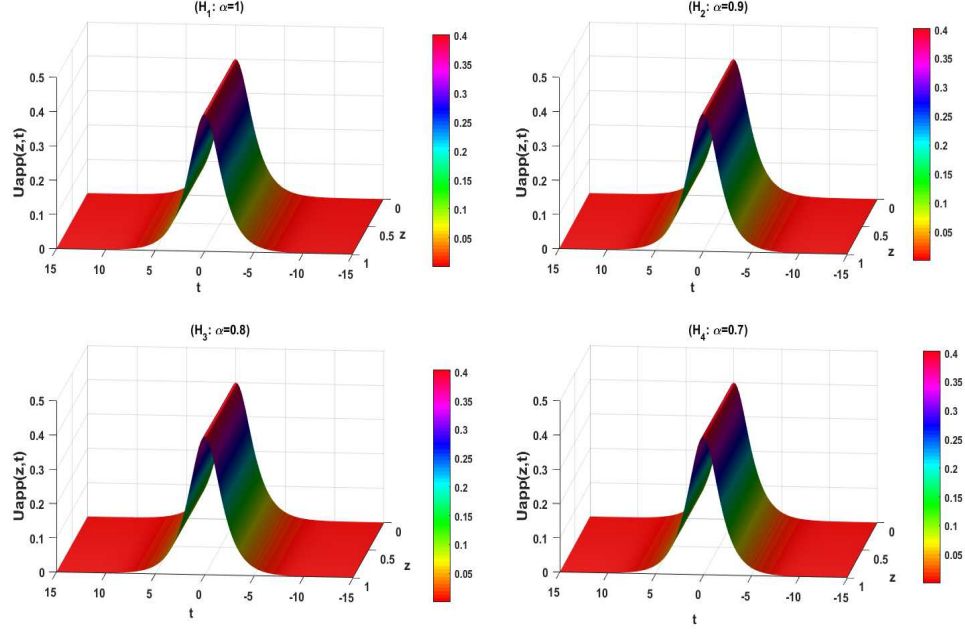


Figure 4: The approximate bright soliton solution obtained by Adomian decomposition method of the equation (28) when $(\alpha = 1, \alpha = 0.9, \alpha = 0.8, \alpha = 0.7)$, $\omega_0 = 0.032 \text{ rad.s}^{-1}$, $C_0 = 100.045 \text{ pH}$, $C_L = 78.65 \text{ pH}$, $L_L = 200.054 \text{ nH}$, $\rho = 0.01$, $k = 0.7, D = 0.084$.

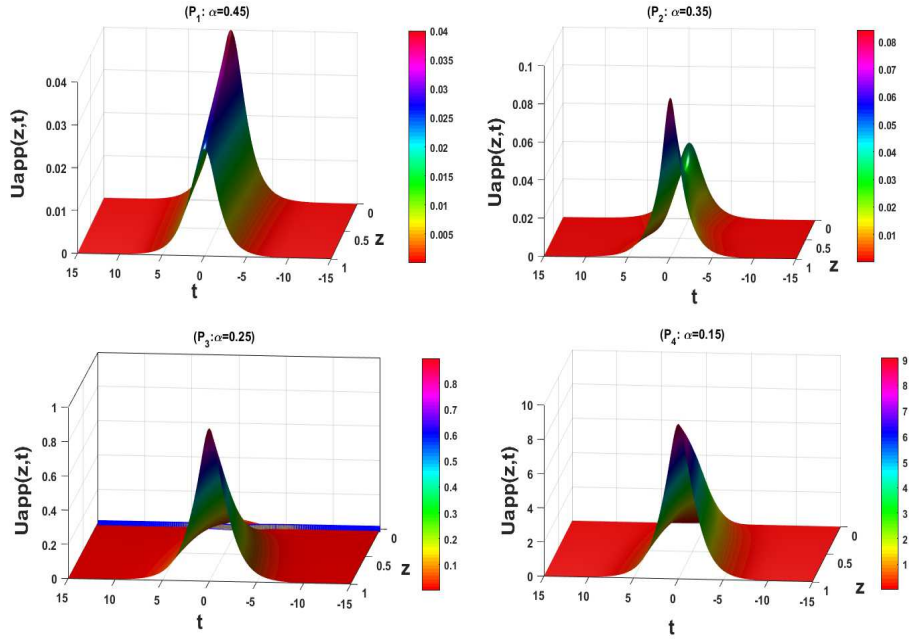


Figure 5: The approximate bright soliton solution obtained by Adomian decomposition method of the equation (28) when $(\alpha = 0.45, \alpha = 0.35, \alpha = 0.25, \alpha = 0.15)$, $\omega_0 = 0.032 \text{ rad.s}^{-1}$, $C_0 = 100.045 \text{ pH}$, $C_L = 78.65 \text{ pH}$, $L_L = 200.054 \text{ nH}$, $\rho = 0.01$, $k = 0.7, D = 0.084$.

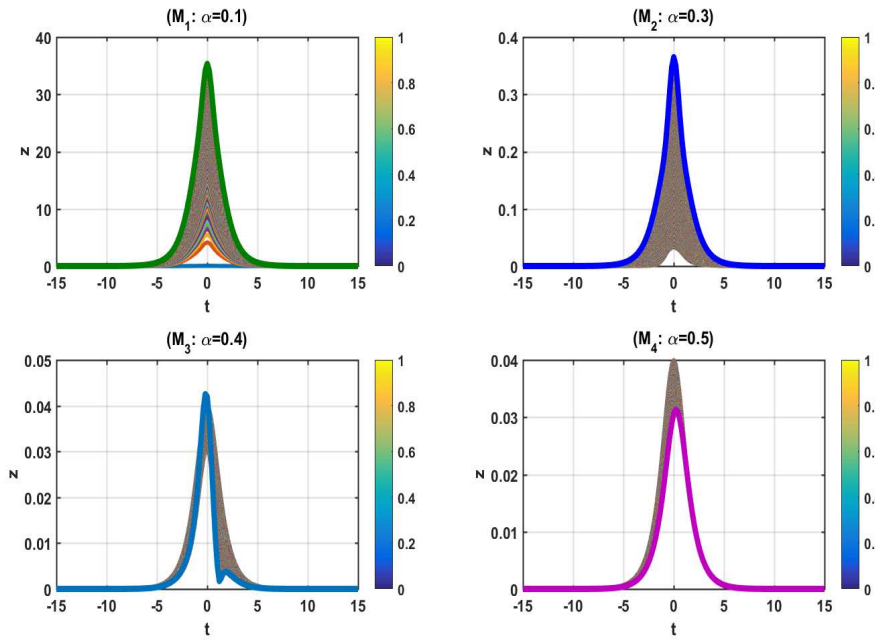


Figure 6: The approximate bright soliton solution obtained by Adomian decomposition method of the equation (28) when $(\alpha = 0.1, \alpha = 0.3, \alpha = 0.4, \alpha = 0.5)$, $\omega_0 = 0.032 \text{ rad.s}^{-1}$, $C_0 = 100.045 \text{ pH}$, $C_L = 78.65 \text{ pH}$, $L_L = 200.054 \text{ nH}$, $\rho = 0.01$, $k = 0.95$, $D = 0.084$.

Table 1: Comparison between the absolute value of the approximate dark soliton solution obtained by Adomian decomposition method of the equation (25) and the absolute value of the exact solution when $(\alpha = 1)$, $\omega_0 = 0.032 \text{ rad.s}^{-1}$, $C_0 = 500.045 \text{ pH}$, $C_L = 478.65 \text{ pH}$, $L_L = 200.0540 \text{ nH}$, $\rho = 0.01$, $k = 0.75$.

N=1,2,...10	abs(U_{app})	abs(U_{exact})	Error (U_{app}) - (U_{exact})
1	0.7531	0.9951	0.2420
2	0.7531	0.9951	0.2420
3	0.7531	0.9951	0.2420
4	0.7531	0.9951	0.2420
5	0.7531	0.9951	0.2420
6	0.7531	0.9951	0.2420
7	0.7531	0.9951	0.2420
8	0.7531	0.9951	0.2420
9	0.7531	0.9951	0.2420
10	0.7531	0.9951	0.2420

$$\begin{pmatrix} jK - (\Omega)^{2\alpha} \beta_2 \frac{j^{-\alpha}}{(2\alpha)!} - 2\beta_2 (\Omega)^\alpha \frac{j^{-\alpha}}{(2\alpha)!} & 2T_4 P \\ 2T_4 P & -jK - (-\Omega)^{2\alpha} \beta_2 \frac{j^{-5\alpha}}{(2\alpha)!} - 2(-\Omega)^\alpha \frac{j^{-3\alpha}}{(2\alpha)!} \end{pmatrix} \begin{pmatrix} a_1 \\ a_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}, \quad (33)$$

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the obtained 2×2 matrix has a non trivial solution when the determinant vanishes. So, the determinant linked with this matrix can read as

$$K^2 + B - 4T_4^2 P^2 = 0, \quad (34)$$

and we show that the general solution is valid unless :

$$K = \pm 2T_4 P \sqrt{1 - \frac{B}{4P^2 T_4^2}}, \quad (35)$$

$$\text{with } B = ((\Omega)^{2\alpha} \beta_2 \frac{j^{-\alpha}}{(2\alpha)!} + 2\beta_2 (\Omega)^\alpha \frac{j^{-\alpha}}{(2\alpha)!}) ((-\Omega)^{2\alpha} \beta_2 \frac{j^{-5\alpha}}{(2\alpha)!} + 2\beta_2 (-\Omega)^\alpha \frac{j^{-3\alpha}}{(2\alpha)!}).$$

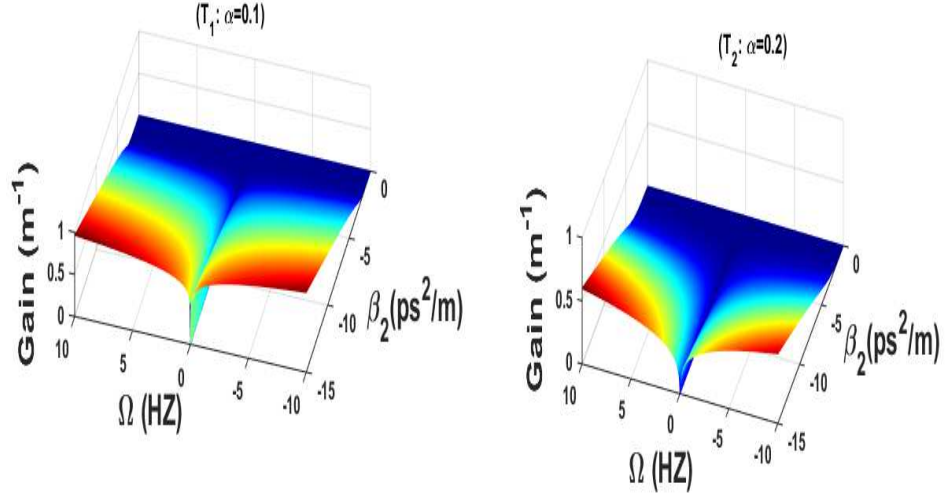


Figure 7: The variation of the (MI) Gain spectrum versus Group velocity dispersion of the (LHNLTTL) of equation (35) when $(\alpha = 0.1, \alpha = 0.2)$, $\omega_0 = 0.52 \text{ rad.s}^{-1}$, $C_0 = 100.6 \text{ pH}$, $C_L = 500.65 \text{ pH}$, $L_L = 400.2 \text{ nH}$, $\rho = 20.02$, $P = 120$.

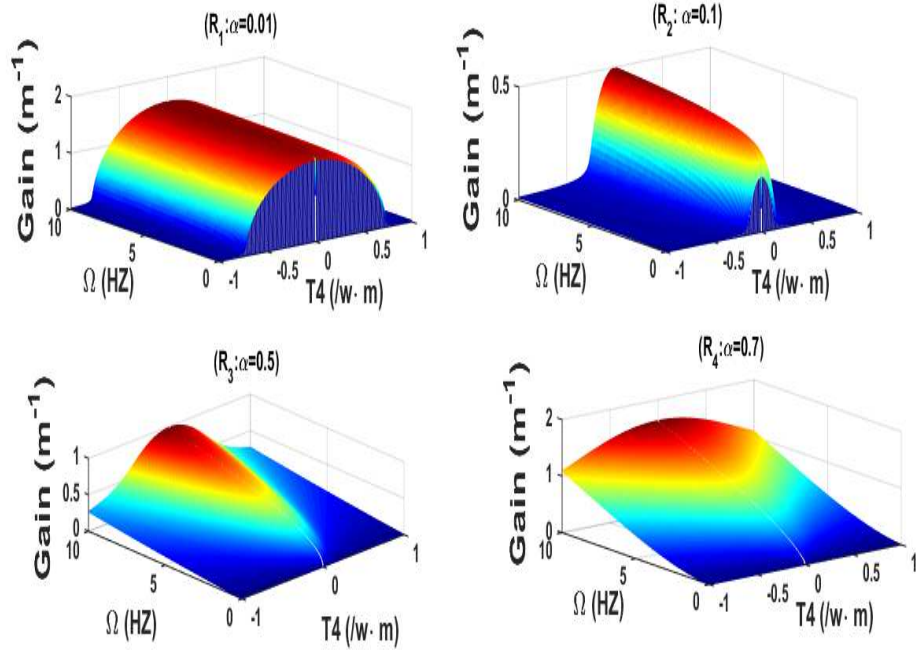


Figure 8: The variation of the (MI) Gain spectrum versus the kerr nonlinearity of the (LHNLTTL) of equation (35) when $(\alpha = 0.01, \alpha = 0.1, \alpha = 0.5, \alpha = 0.7)$, $\omega_0 = 0.32 \text{ rad.s}^{-1}$, $C_0 = 70.6 \text{ pH}$, $C_L = 450.65 \text{ pH}$, $L_L = 420.2 \text{ nH}$, $\rho = 0.002$, $P = 0.5$.

Table 2: Comparison between the absolute value of the approximate dark soliton solution obtained by Adomian decomposition method of the equation (25) and the absolute value of the exact solution when $(\alpha = 0.5)$, $\omega_0 = 0.032 \text{ rad.s}^{-1}$, $C_0 = 500.045 \text{ pH}$, $C_L = 478.65 \text{ pH}$, $L_L = 200.0540 \text{ nH}$, $\rho = 0.01$, $k = 0.75$.

N=1,2,...10	abs(U_{app})	abs(U_{exact})	Error (U_{app}) - (U_{exact})
1	0.7531	0.9951	0.2420
2	0.7528	0.9920	0.2392
3	0.7526	0.9890	0.2364
4	0.7523	0.9860	0.2337
5	0.7520	0.9830	0.2310
6	0.7517	0.9800	0.2282
7	0.7514	0.9770	0.2256
8	0.7511	0.9740	0.2229
9	0.7508	0.9710	0.2203
10	0.7504	0.9681	0.2177

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4. Physical explanation of the results

Figures 1 and 2 show the pipe of the dark soliton solutions with the effect of the fractional derivative order in nonlinear left-handed transmission line for $\omega_0 = 0.032 \text{ rad.s}^{-1}$, $C_0 = 100.045 \text{ pH}$, $C_L = 78.65 \text{ pH}$, $L_L = 200.054 \text{ nH}$, $\rho = 0.01$, $k = 0.98$. The effect of the fractional order are pointed out when $\alpha = 0.5$, $\alpha = 0.45$, $\alpha = 0.4$ and $\alpha = 0.35$ (see figure 2). In addition the shape of the wave undergoes deformations as α takes small values and this reflects the phenomenon of the memory effect which is one of the advantages linked to the fractional derivative order. On the other hand, for values of α tending towards 1, the result obtained is similar to the dark soliton solution known in the left-handed metamaterials. We also emphasized the behavior of

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Table 3: Comparison between the absolute value of the approximate dark soliton solution obtained by Adomian decomposition method of the equation (25) and the absolute value of the exact solution when $(\alpha = 0.2)$, $\omega_0 = 0.032 \text{ rad.s}^{-1}$, $C_0 = 500.045 \text{ pH}$, $C_L = 478.65 \text{ pH}$, $L_L = 200.0540 \text{ nH}$, $\rho = 0.01$, $k = 0.75$.

N=1,2,...10	abs(U_{app})	abs(U_{exact})	Error (U_{app}) - (U_{exact})
1	0.7531	0.9951	0.2420
2	2.4983	3.1348	0.6365
3	4.7712	6.0274	1.2562
4	6.9457	8.7256	1.7799
5	9.0417	11.2942	2.2526
6	11.0746	13.7666	2.6920
7	13.0553	16.1628	3.1075
8	14.9918	18.4963	3.5044
9	16.8900	20.7764	3.8865
10	18.7544	23.0105	4.2561

the bright soliton solutions with the effect of the fractional derivative order in figures 4-6 for $\omega_0 = 0.032 \text{ rad.s}^{-1}$, $C_0 = 100.045 \text{ pH}$, $C_L = 78.65 \text{ pH}$, $L_L = 200.054 \text{ nH}$, $\rho = 0.01$, $k = 0.7$, $k = 0.95$, $D = 0.084$. Moreover, the effect of fractional order on the width of the bright soliton is obtained (see Figures 5 and 6). More precisely, the solitons obtained took into account the terms of nonlinearity and of dispersion for their existence. As it is mentioned in several works that the nonlinearity and dispersion terms involve the modulation instability, we have set out the dynamic of the variation of MI gain spectra in the anomalous group velocity dispersion on the one hand and on the other hand the nonlinear term kerr. It is observed the instability zones when the derivative order α is near to 1 (see figures 8 (R_3, R_4)). It should be noted that the instability is linked to MI due to unbidden temporal modulation of the continuous wave (CW) stack and change it into a pulse train. However, for the small value of the fractional derivative order stability zones appeared (see

Table 4: Comparison between the absolute value of the approximate bright soliton solution obtained by Adomian decomposition method of the equation (28) and the absolute value of the exact solution when $(\alpha = 1)$, $\omega_0 = 0.032 \text{ rad.s}^{-1}$, $C_0 = 500.045 \text{ pH}$, $C_L = 478.65 \text{ pH}$, $L_L = 200.0540 \text{ nH}$, $\rho = 0.01$, $k = 0.75$.

N=1,2,...10	abs(U_{app})	abs(U_{exact})	Error (U_{app}) - (U_{exact})
1	0.0038	0.0039	0.1622e-03
2	0.0038	0.0039	0.1622e-03
3	0.0038	0.0039	0.1622e-03
4	0.0038	0.0039	0.1622e-03
5	0.0038	0.0039	0.1622e-03
6	0.0038	0.0039	0.1622e-03
7	0.0038	0.0039	0.1622e-03
8	0.0038	0.0039	0.1622e-03
9	0.0038	0.0039	0.1622e-03
10	0.0038	0.0039	0.1622e-03

figures 8 (R_1, R_2)). Enough but not the last, we use MATLAB calculation to dig out the gap between the approximate analytical results and the exacts. From tables 1 and 4 it is observed that when the value of derivative order tends to 1 the $U_{app} \approx U_{exact}$. It is also observed that the difference is greater between the exact obtained and the results of the estimation when the values of the order of the derivatives are too small (see tables 2, 3, 5 and 6). So, these results obtained are new and significant because dark and bright solitons were obtained by the adomian decomposition method in a nonlinear left-handed transmission line with the variable (t) less than, greater than or equal to zero. We deduce that the behavior of the approximate bright solutions is practically the same as the behavior of its exact solution with different values of α and we obtain small errors between the approximate solution and the exact solution for certain values of α with the number of steps. On the other hand, the behavior of dark approximate solutions and the behavior of its exact solution, leads us to large

Table 5: Comparison between the absolute value of the approximate bright soliton solution obtained by Adomian decomposition method of the equation (28) and the absolute value of the exact solution when $(\alpha = 0.5)$, $\omega_0 = 0.032 \text{ rad.s}^{-1}$, $C_0 = 500.045 \text{ pH}$, $C_L = 478.65 \text{ pH}$, $L_L = 200.0540 \text{ nH}$, $\rho = 0.01$, $k = 0.75$.

N=1,2,...10	abs(U_{app})	abs(U_{exact})	Error (U_{app}) - (U_{exact})
1	0.0038	0.0039	0.1622e-03
2	0.0038	0.0039	0.1622e-03
3	0.0037	0.0039	0.1622e-03
4	0.0037	0.0039	0.1623e-03
5	0.0037	0.0039	0.1623e-03
6	0.0037	0.0038	0.1623e-03
7	0.0037	0.0038	0.1623e-03
8	0.0036	0.0038	0.1623e-03
9	0.0036	0.0038	0.1623e-03
10	0.0036	0.0038	0.1623e-03

errors for some α values with the number of steps. Therefore, we infer that the bright soliton is more convergent than the dark soliton. This work could therefore be very interesting.

5. Summary

280 In this work, the Adomian decomposition method (ADM) has been successfully applied to obtain semi-analytic solutions of the fractional nonlinear Schrödinger equation with initial conditions. Efficiency, power, reliability and reduced calculations of this approach give it a wider applicability. Figures 1, 2 and 3 show the behavior of the dark soliton with the influence of the fractional
285 derivative order. More precisely, the shape and amplitude of the wave are obtained with deeply small values of the derivative order. Concerning the bright soliton solutions it is also pointed out the same phenomenon observed previously to the dark solitons. As mentioned above, the divergence between kerr nonlin-

Table 6: Comparison between the absolute value of the approximate bright soliton solution obtained by Adomian decomposition method of the equation (28) and the absolute value of the exact solution when $(\alpha = 0.2)$, $\omega_0 = 0.032 \text{ rad.s}^{-1}$, $C_0 = 500.045 \text{ pH}$, $C_L = 478.65 \text{ pH}$, $L_L = 200.0540 \text{ nH}$, $\rho = 0.01$, $k = 0.75$.

N=1,2,...10	abs(U_{app})	abs(U_{exact})	Error (U_{app}) - (U_{exact})
1	0.0038	0.0039	0.0002
2	0.0236	0.0236	0.0001
3	0.0438	0.0438	0.0000
4	0.0620	0.0621	0.0002
5	0.0789	0.0793	0.0004
6	0.0951	0.0957	0.0007
7	0.1106	0.1116	0.0010
8	0.1256	0.1269	0.0013
9	0.1401	0.1418	0.0016
10	0.1543	0.1563	0.0020

earity and group velocity terms is favorable to MI, then the MI gain spectrum
 290 versus anomalous group velocity dispersion and nonlinearity coefficient is also
 shown (see figures 7 and 8). Several instability zones are obtained under the
 effect of the derivative order. Beside these results, we obtain the errors between
 the approximate and the exacts dark (bright) solitons solutions (see tables 1,
 2, 3, 4, 5 and 6). Therefore, we deduce that the approximate solution is con-
 295 vergent series as an exact solution [27]. The Adomian decomposition method is
 a very efficient and powerful technique for finding soliton solutions. However,
 interpretation of the results reveals that the propagation of the wave is consid-
 erably disturbed when moving away with the effect of the derivative order, so
 that the evolution of the system can no longer be controlled. Nevertheless, these
 300 results are more precise than that in [39, 40] because in this work, we obtain
 both dark and bright solitons with the effect of fractional derivatives order by
 applying the Adomian decomposition method (ADM) to this same equation (1)

of [39, 40] and we also evaluated the modulational instability of these solitons. Since, analytical and numerical studies of the metamaterial transmission line
305 have proven the presence of Schrödinger solitons, which has led us to formation of dark Schrödinger solitons in this nonlinear left-handed transmission line by applying the Adomian decomposition method (ADM) to the equation (1) of [39, 40] with the effect of fractional derivatives order. Finally, this nonlinear left-handed transmission line with the effect of the fractional derivative order
310 also allowed us to generate bright envelope solitons by making an appropriate choice of the values of the fractional derivative order and the initial condition.

Author contributions

All authors contributed significantly to this article and have read and
315 approved the final manuscript.

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Declaration of Competing Interest

The authors declare that they have no known competing financial inter-
320 ests or personal relationships that could have appeared to disrupt the work done in this article.

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Figures

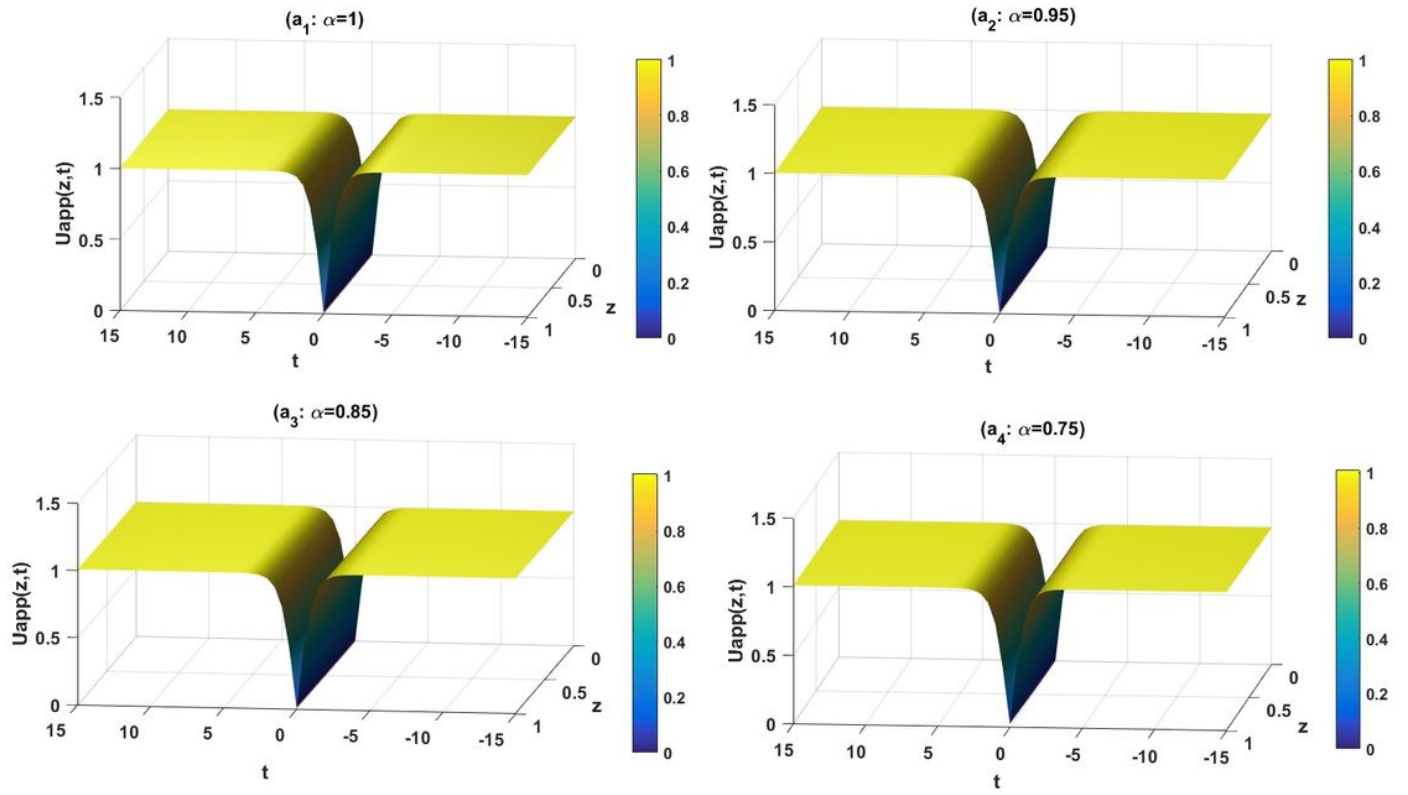


Figure 1

The approximate dark soliton solution obtained by Adomian decomposition method of the equation (25) (see Manuscript file for full figure legend)

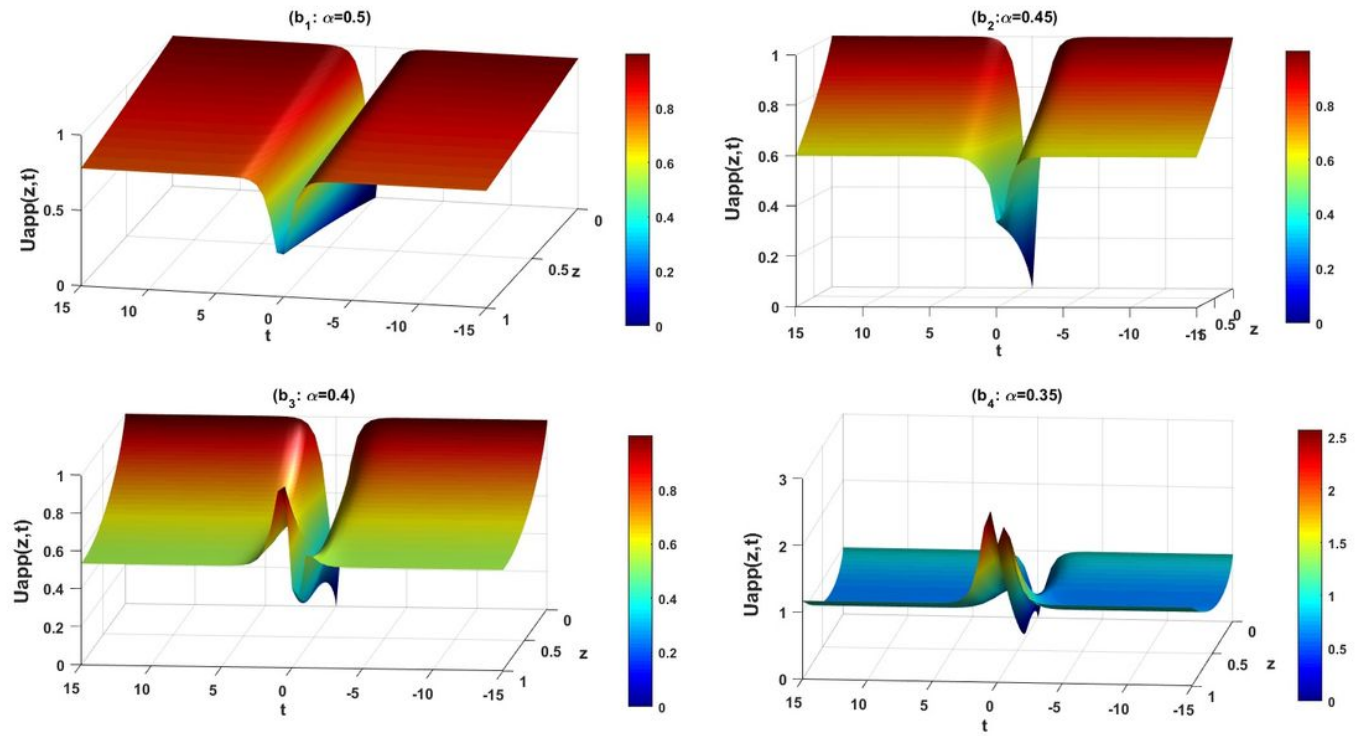


Figure 2

The approximate dark soliton solution obtained by Adomian decomposition method of the equation (25) (see Manuscript file for full figure legend)

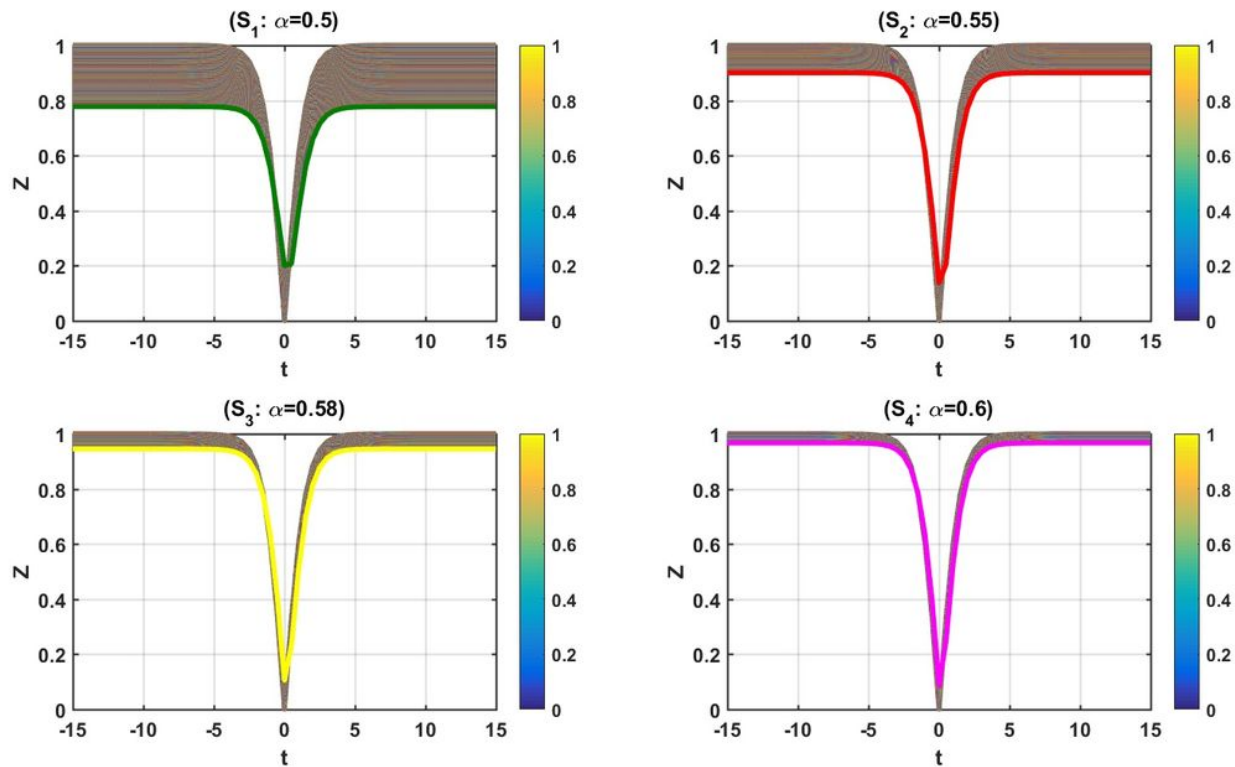


Figure 3

The approximate dark soliton solution obtained by Adomian decomposition method of the equation (25) (see Manuscript file for full figure legend)

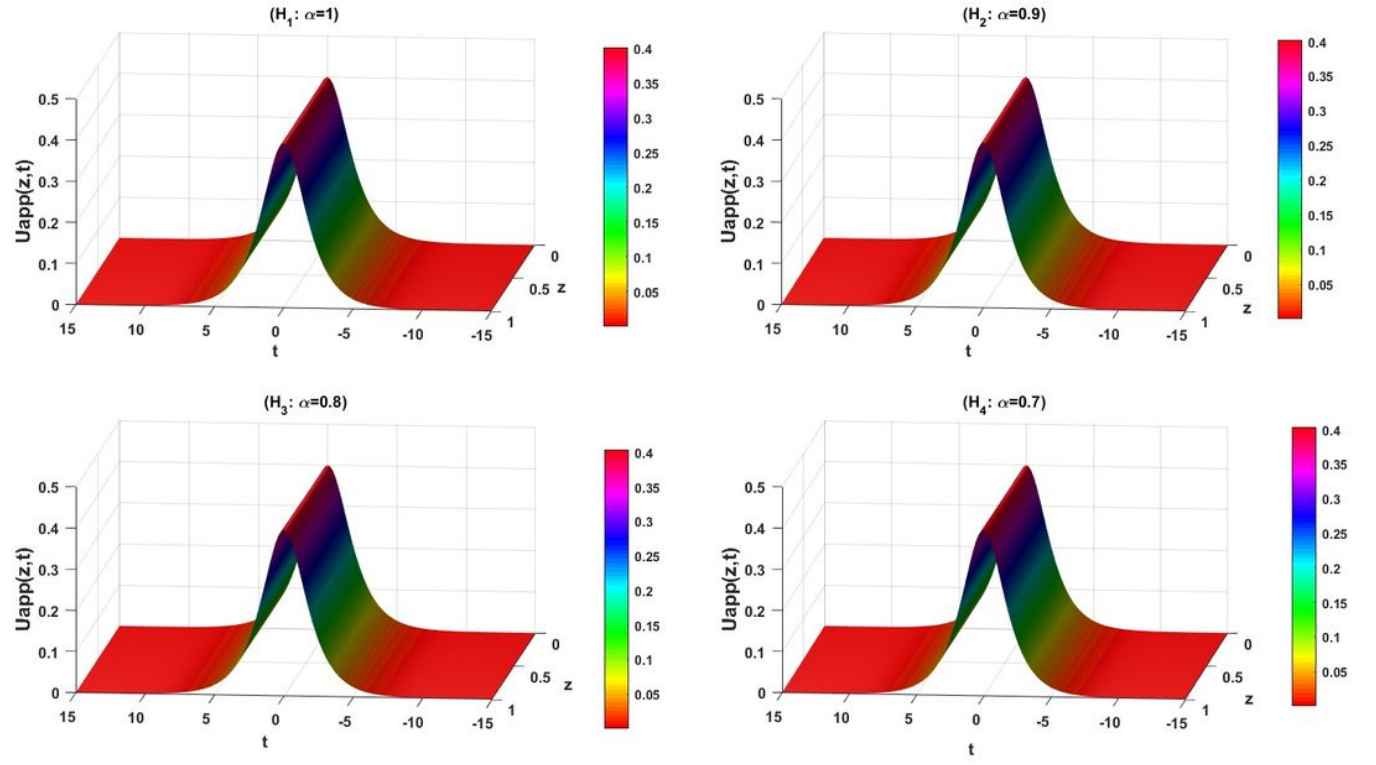


Figure 4

The approximate bright soliton solution obtained by Adomian decomposition method of the equation (28) (see Manuscript file for full figure legend)

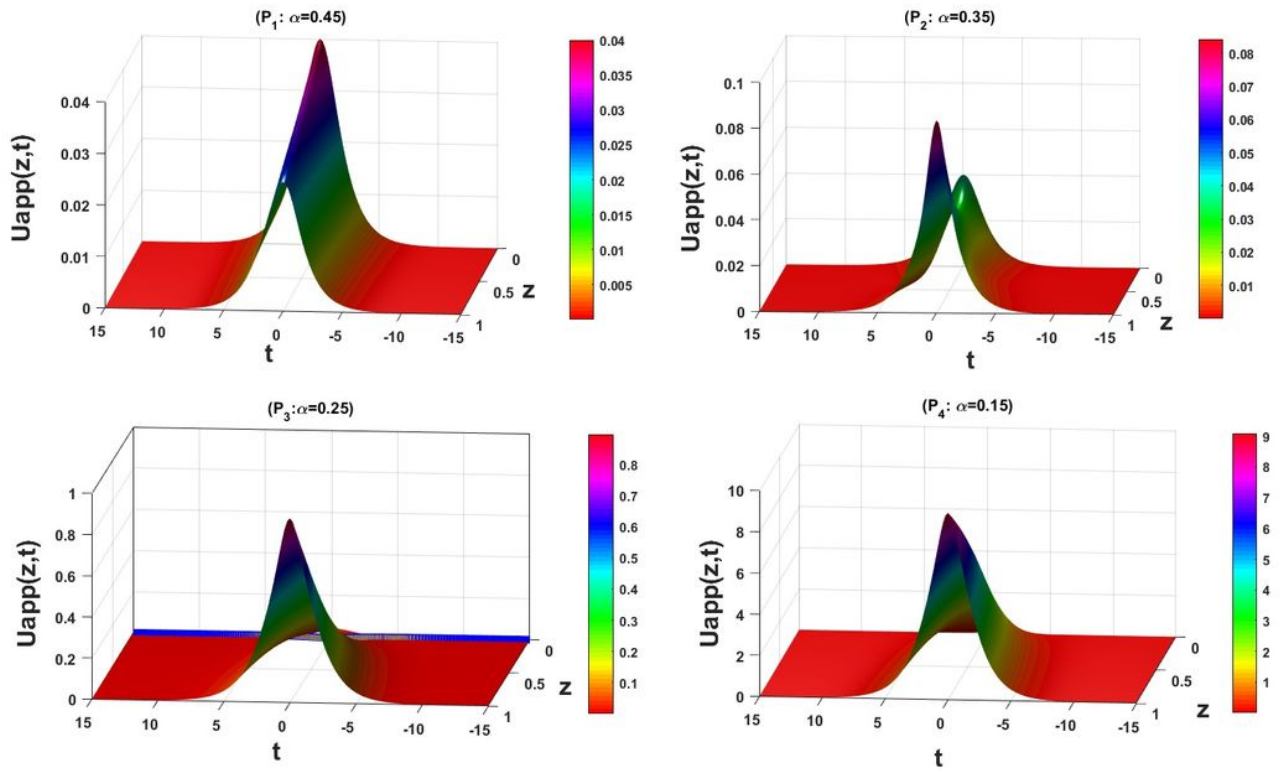


Figure 5

The approximate bright soliton solution obtained by Adomian decomposition method of the equation (28) (see Manuscript file for full figure legend)

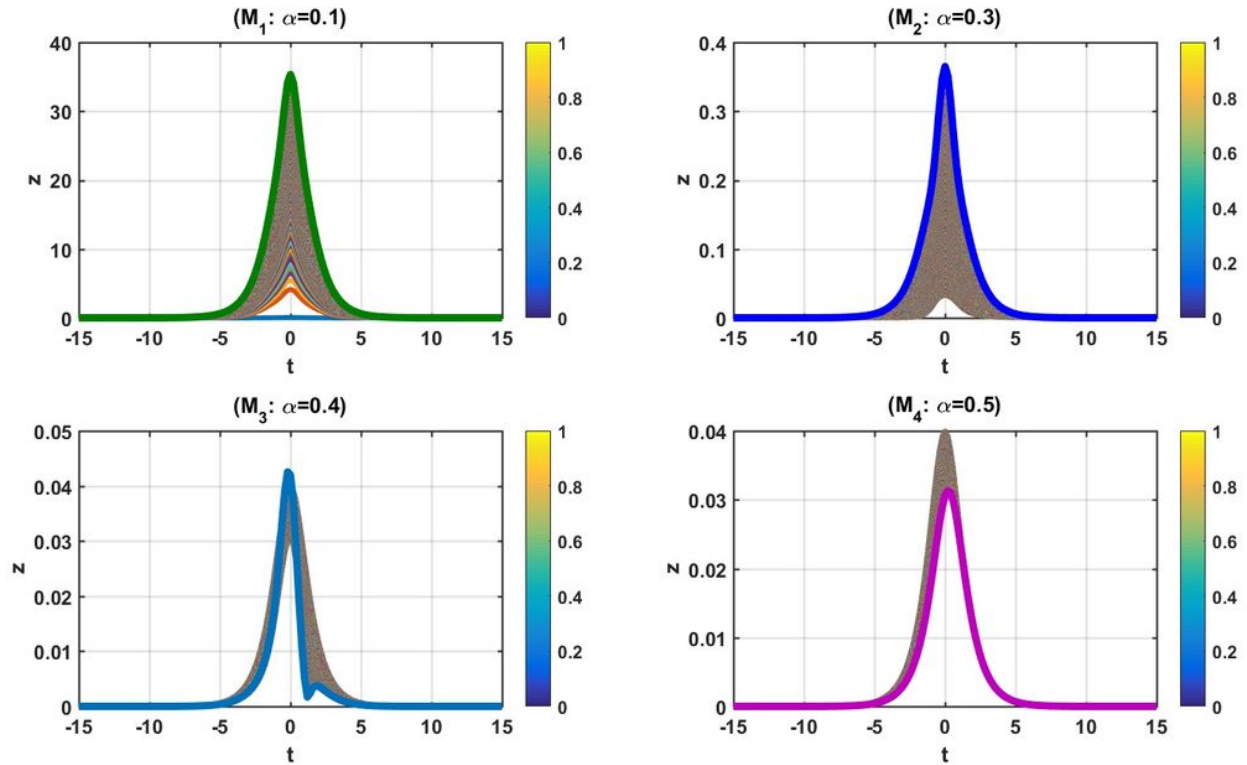


Figure 6

The approximate bright soliton solution obtained by Adomian decomposition method of the equation (28)(see Manuscript file for full figure legend)

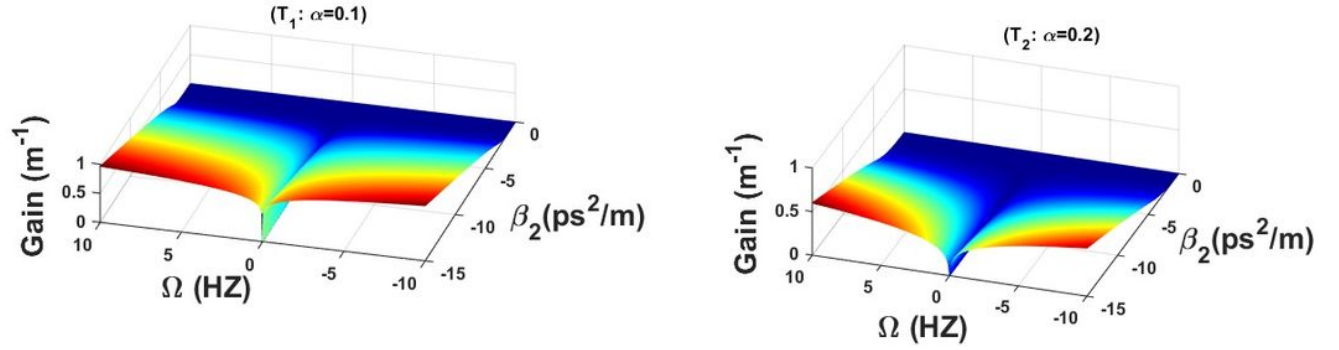


Figure 7

The variation of the (MI) Gain spectrum versus Group velocity dispersion of the (LHNLTL) of equation (35) (see Manuscript file for full figure legend)

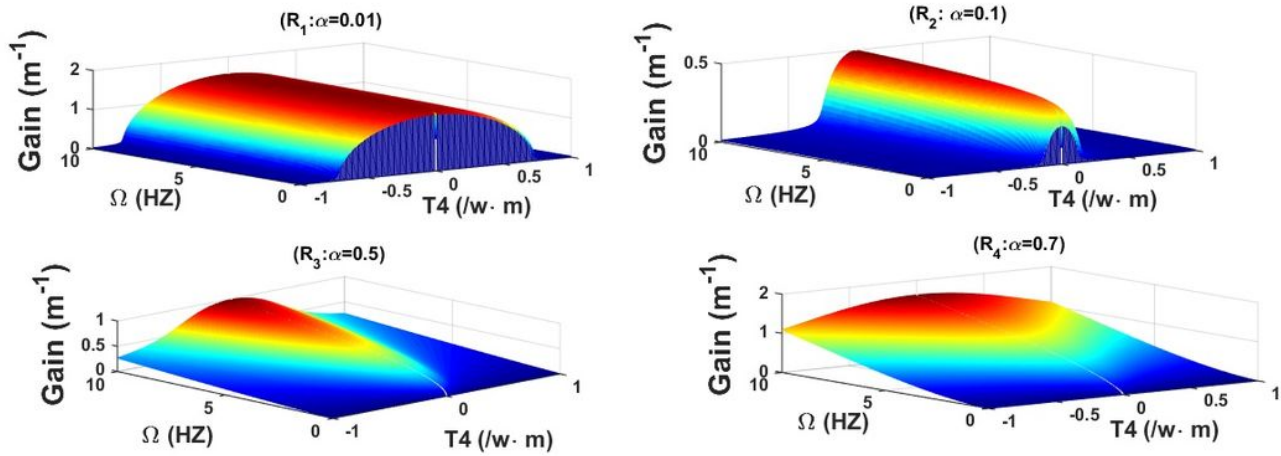


Figure 8

The variation of the (MI) Gain spectrum versus the kerr nonlinearity of the (LHNLTL) of equation (35) (see Manuscript file for full figure legend)