

NEMA NU 1-2018 performance characterization and Monte Carlo model validation of the Cubresa Spark SiPM-based preclinical SPECT scanner

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ORIGINAL RESEARCH

NEMA NU 1-2018 performance characterization and Monte Carlo model validation of the Cubresa Spark SiPM-based preclinical SPECT scanner

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Abstract

Background: The Cubresa Spark is a novel benchtop silicon-photomultiplier (SiPM)-based preclinical SPECT system. SiPMs in SPECT significantly improve resolution and reduce detector size compared to preclinical cameras with photomultiplier tubes requiring highly magnifying collimators. The NEMA NU 1 Standard for Performance Measurements of Gamma Cameras provides methods that can be readily applied or extended to characterize preclinical cameras with minor modifications. The primary objective of this study is to characterize the Spark according to the NEMA NU 1-2018 standard to gain insight into its nuclear medicine imaging capabilities. The secondary objective is to validate a GATE Monte Carlo simulation model of the Spark for use in preclinical SPECT studies.

Methods: NEMA NU 1-2018 guidelines were applied to characterize the Spark's intrinsic, system, and tomographic performance with single- and multi-pinhole collimators. Phantoms were fabricated according to NEMA specifications with deviations involving high-resolution modifications. GATE was utilized to model the detector head with the single-pinhole collimator, and NEMA measurements were employed to tune and validate the model. Single-pinhole and multi-pinhole SPECT data were reconstructed with the Software for Tomographic Image Reconstruction and HiSPECT, respectively.

Results: The limiting intrinsic resolution was measured as 0.85 mm owing to a high-resolution SiPM-array combined with a 3 mm-thick scintillator. The average limiting tomographic resolution was 1.37 mm and 1.19 mm for the single- and multi-pinhole collimators, respectively, which have magnification factors near unity at the center of rotation. The maximum observed count rate was 15,400 cps, and planar sensitivities of 34 cps/MBq and 150 cps/MBq were measured at the center of rotation for the single- and multi-pinhole collimators, respectively. All simulated tests agreed well with measurement, where the most considerable deviations were below 7%.

Conclusions: NEMA NU 1-2018 standards determined that a SiPM detector mitigates the need for highly magnifying pinhole collimators while preserving detailed information in projection images. Measured and simulated NEMA results were highly comparable with differences on the order of a few percent, confirming simulation accuracy and validating the GATE model. The multi-pinhole collimator investigated in this study offers the optimal combination of resolution and sensitivity for organ-specific imaging of small animals, and the single-pinhole collimator enables high-resolution whole-body imaging of small animals.

Keywords: Molecular Imaging; Nuclear Medicine; SPECT; Animal Imaging Instrumentation; Monte Carlo Method; Computer-Assisted Image Processing; Imaging Phantoms

Introduction

Functional imaging in nuclear medicine extensively employs positron emission tomography (PET) and single-photon emission computed tomography (SPECT) for disease diagnosis and staging, therapy planning, dosimetry, and monitoring of treatment response [1]. These nuclear medicine techniques are based on radiopharmaceutical uptake within the body, yielding critical diagnostic information that can readily translate to developing theranostic strategies for managing various diseases. Such investigations are now commonly performed in the preclinical setting to evaluate the effects of novel drugs and therapies in small animals [2]. Due to the relatively small organ size of mice compared to humans, preclinical imaging demands highresolution technology. Recent advancements in imaging technology have promoted widespread adoption of small-animal imaging, and the availability of dedicated preclinical scanners has increased to satisfy this demand. Some advantages of SPECT over PET include superior spatial resolution, simultaneous multi-energy and multiisotope signature detection, increased accessibility to isotopes with a range of physical half-lives, relatively simple and stable radiochemistry with increased specific activities, and reduced production costs [3, 4]. Therefore, developing sensitive and accurate preclinical SPECT systems is of growing importance. Monte Carlo simulations are also essential in emission tomography investigations to model, develop, and evaluate nuclear-based imaging systems [5]. The Monte Carlo method is considered the gold standard for designing new medical imaging devices, offering an effective means to assess performance, optimize acquisition protocols, and evaluate new image reconstruction algorithms and correction techniques. Several Monte Carlo packages exist including Geometry and Tracking (Geant4) [6], Electron Gamma Shower (EGS) [7], and Monte Carlo N-Particle (MCNP) [8], all of which provide well-validated physics models and geometry modelling tools. These toolkits focus on radiation transport simulations, and tuning the code to model PET and SPECT devices can be challenging. The Geant4 Application for Tomographic Emission (GATE) aims to simplify the modelling process while accommodating complex scanner geometries and imaging configurations using geometric definitions, time-dependent phenomena, radioactive source definitions, detector electronics modelling, and data output [5].

Several commercially available preclinical SPECT detectors have been investigated with GATE, including X-SPECT (TriFoil Imaging, Chatsworth, USA) [9], Inveon (Siemens, Munich, Germany) [10], HiReSPECT (Parto Negar Persia, Tehran, Iran) [11], and NanoSPECT/CTPLUS (Mediso, Budapest, Hungary) [12] scanners. These systems, like all SPECT systems, are constructed with varying component designs, including but not limited to pinhole or parallel-hole collimators, monolithic or pixelated scintillators, and solid-state or vacuum tube detector technologies. Cameras that use photomultiplier tubes (PMTs) for high-resolution preclinical SPECT are large and bulky and require highly magnifying pinhole collimators to overcome

signs, including but not limited to pinhole or parallel-hole collimators, monolithic or
pixelated scintillators, and solid-state or vacuum tube detector technologies. Cameras that use photomultiplier tubes (PMTs) for high-resolution preclinical SPECT
are large and bulky and require highly magnifying pinhole collimators to overcome
the limiting intrinsic spatial resolution of PMTs. While position-sensitive PMTs
(PSPMTs) offer a smaller form factor than PMTs with improved resolution, their
combination with scintillating crystals to detect γ- and X-rays yields a detector
that is also several centimeters thick, and the camera size is further increased when
attaching pinhole or parallel-hole collimators. Recent advancements in solid-state
technology, such as cadmium zinc telluride (CZT) for direct detection or siliconphotomultipliers (SiPMs) coupled with scintillators for indirect detection, provide
advantages over PMT-based technology, including a smaller form factor for design
flexibility, superior intrinsic spatial resolution, reduced power consumption, and insensitivity to magnetic fields and vibrations [13]. An example of a novel SiPM-based
preclinical SPECT scanner is the Cubresa Spark (Cubresa Inc., Winnipeg, Canada).

The Spark is a small-animal benchtop SPECT system optimized for *in vivo* mouse imaging and can be configured with up to two detector heads. Its current configu-

ration features one detector head, single- and multi-pinhole collimators, a sodiumactivated cesium iodide (CsI(Na)) scintillator, and a SiPM array to achieve highresolution planar and tomographic imaging. Altogether, the detector head is less
than 6 cm-thick from the face of the collimator to the exterior of the back compartment housing the electronics. This small form factor makes the Spark suitable for benchtop use. It can also be attached to preclinical computed tomography
(CT) scanners for multi-modal disease study, translational research, and drug discovery applications. For example, it was recently utilized in developing diagnostic
radiopharmaceuticals for Alzheimer's disease [14]. Due to the novelty of SiPMs in
SPECT, the performance characteristics of a preclinical SiPM SPECT scanner have
not been established or compared to other scanners in the literature.

To compare different γ-cameras, the National Electrical Manufacturers Association (NEMA) has published the NEMA NU 1-2018 Standard for Performance Measurements of Gamma Cameras [15]. This standard provides a uniform and consistent method for measuring and reporting performance parameters for various camera designs. Although NEMA has published a *clinical* and *preclinical* standard for PET scanners, a preclinical SPECT standard is currently unavailable. However, the NEMA NU 1-2018 clinical standard can be readily applied or extended to preclinical SPECT cameras with minor modifications. NEMA standards also provide a rigorous and thorough approach to validating Monte Carlo models, unlike the systems above modelled in GATE that used widely varying, incomplete, or untraceable validation approaches in some cases.

The primary objective of this study is to evaluate the performance characteristics
of a high-resolution SiPM-based preclinical SPECT scanner — the Cubresa Spark —
according to the NEMA NU 1 Standard for Performance Measurements of Gamma
Cameras. A secondary objective is to configure and validate a GATE simulation
model of the Spark using the measured NEMA results. Collectively, this study aims

- to accurately establish the imaging performance of a SiPM SPECT system in planar
- and tomographic acquisitions offering critical insight into its utility in supporting
- the development of novel molecular imaging agents and techniques.

85 Methods and materials

- 86 Equipment description
- 37 The Spark (Fig. 1) was affixed to the benchtop of a Triumph LabPET4/CT dual-
- 88 modality system (TriFoil Imaging, Chatsworth, USA). Its detector housing was
- manufactured from tungsten and assembled with a $102 \times 102 \times 3$ mm³ monolithic
- oc CsI(Na) scintillator (Saint-Gobain Crystals, Hiram, USA) and a 14×14 SensL C-
- 91 series SiPM array with 6 mm sensors (ON Semiconductor, Phoenix, USA). As out-
- 92 lined in Table 1, the Spark performance was assessed with two interchangeable
- tungsten collimators (Scivis GmbH, Göttingen, Germany): a single-pinhole (SPH)
- collimator for high-resolution planar and tomographic imaging, and a multiplexing
- multi-pinhole (MPH) collimator for high-resolution tomography with increased sen-
- sitivity. The SPH collimator has a non-focusing right-circular double-cone pinhole,
- $_{97}$ and the MPH collimator uses a 5×5 array of focusing right-circular double-cone
 - pinholes where each row focuses on a different volume of interest (VOI) in the to-
- mographic field of view (FOV) [16]. The area of the detector used for imaging γ -
- and X-rays has a useful field of view (UFOV) and central field of view (CFOV) of
- 84.5 mm and 63.375 mm, respectively, as defined by the collar of the collimators.

$_{102}$ \rightarrow Figure 1 goes here.

Table 1 Geometric specifications of pinhole collimators.

Aperture $^{[1]}$	SPH	MPH
Pinhole diameter (mm)	1.0	1.0
Pinhole acceptance angle (°)	90.0	25.0
Number of pinholes	1	25
Thickness (mm)	10.0	10.0
Radius of rotation (mm)	28.0	28.0
Aperture-to-detector distance ^[2] (mm)	26.75	26.75
Reconstructed axial FOV (mm)	57.0	14.0
Reconstructed transaxial FOV (mm)	46.0	30.0

^[1]SPH: Single-pinhole, MPH: Multi-pinhole

^[2] Measured to face of scintillator

The Spark was delivered with Scivis' HiSPECT reconstruction software, which was preconfigured solely for the MPH collimator. Precise information regarding the MPH collimator geometry was not readily available, and as a result, this restricted the simulation model to the SPH collimator only. Measured and simulated SPH SPECT images were reconstructed with prototype code developed for the open-source Software for Tomographic Image Reconstruction (STIR) [17, 18, 19]. This reconstruction code is currently under development and will be the focus of future work; however, details will be provided as necessary when used in this work. Prior to measurement, the SPECT system was calibrated for energy, linearity, uni-formity, center of rotation, and aperture-to-detector distance [20, 21]. Radionuclide activity measurements were performed with a Capintec CRC-55tR dose calibrator (Mirion Technologies, Florham Park, USA). Various phantoms and source position-ing jigs were fabricated in-house to adhere to the NEMA protocol, and each required

117 Simulation description

device is described in the following sections.

tem in the GATE v9.0 Monte Carlo toolkit [5] compiled with Geant4 10.06.p01 [6] and Rapid Object-Oriented Technology (ROOT) 6.14.04 [22]. Simulations were dis-tributed over 12 cores on an HP Z820 workstation operating Ubuntu 18.04.5 LTS with two Intel Xeon E5-2630 2.3 GHz hexa-core CPUs and 64 GB of 1600 MHz DDR3 memory. ROOT output was combined into one file and then converted to Cubresa's list mode format for further processing. Complex detector geometry was modelled with standard tessellation language (STL) files provided by Cubresa, and simple geometric volumes were modelled with predefined shapes available in GATE. Note that the animal bed and MPH collimator were excluded from simulation. The SPH collimator was modelled with a 0.85 mm diameter pinhole to better match the simulated collimator-detector response func-

A model of the Spark detector head (Fig. 1) was created using the SPECThead sys-

tion to measurement. Physics processes were initialized with the Geant4 standard electromagnetic physics package option 4 (emstandard opt4) [6]. Particle produc-tion cuts were set at the default value of 1 mm corresponding to a few keV in most materials, except the scintillator and pinhole knife-edge where the threshold was set to 1 keV. Radioactive sources were defined as an isotropic UserSpectrum source of γ -rays with isotope spectra defined from the Table of Radionuclides [23]. The scin-tillation process, optical photon transport, and light detection were not simulated to save computing time. The signal processing chain of the simulation was modelled using the following digitizer modules: the adder, readout, energy blurring, spatial blurring, pile-up, dead time, and efficiency. Figure 2 presents the digitizer chain with the values set for parameters of interest. All simulation parameters were deduced from measurement

$$t_{\min} = \frac{P_1}{R_{\mathrm{T}}(P_0 + 2P_1)} \tag{1}$$

except for the pile-up timing resolution t_{\min} , which was calculated as

where P_0 and P_1 are the counts in the primary and first order pile-up peaks, respectively, and $R_{\rm T}$ is the true input count rate [24].

 $_{146}$ \rightarrow Figure 2 goes here.

NEMA performance characterization and SPECT model validation

Performance characterization of the Spark was made according to the NEMA NU
1-2018 protocol, with tests briefly described in the following sections. The radionuclide for all tests was technetium-99m (^{99m}Tc) unless stated otherwise. Projection
images of the UFOV and CFOV were generated with electronic masking using 30%wide energy windows centered on the reference photopeak(s), and 0.1 mm isotropic
pixels were used unless stated otherwise. Measured data were acquired according to
total acquisition time or counts through an open energy window. Simulations were

then configured based on measurements of data acquisition time, radioactivity, radioactive source distribution, and system geometry, except for the SPH collimator
pinhole diameter. No corrections were applied to the simulated data at any stage.
Validation of the GATE model was based on reporting parameter comparisons between measured and simulated NEMA results.

$_{160}$ Tests of intrinsic gamma camera detector characteristics

Intrinsic spatial resolution and linearity Intrinsic spatial resolution refers to the γ -camera's ability to localize an ionizing photon's interaction site within the detector, and intrinsic linearity reflects the dis-tortion of those interaction sites throughout the detector's FOV. This test was performed with a 2.5 mm-thick tungsten planar mask comprised of a 3×3 grid of 0.8 mm-wide and 26.5 mm-long parallel slits having adjacent slit centers separated by 31.5 mm, and a Derenzo pattern with {0.7, 0.8, 0.9, 1.0, 1.2, and 1.4} mm diameter holes. An Eppendorf tube containing a 50 MBq point source was centered 65 cm above the face of the detector, and 15 million counts were acquired. Intrinsic resolution and linearity were assessed from line spread functions (LSFs) and an-alyzed according to the procedures defined by the NEMA NU 1-2018 protocol. A millimeters-per-pixel calibration factor was also calculated using line profile spacing to convert relevant image dimensions to physical units in relevant NEMA tests. Note that the mask-slit geometry above did not yield the limiting spatial resolu-tion. Therefore, a secondary test was performed with a pencil beam to measure the limiting resolution from a point spread function (PSF). A pencil beam was created with a tungsten line-source holder with a tunnel 0.4 mm in diameter (\varnothing), 10.0 mm in length (L), and centered 1.0 mm above the detector with a 1.0 cm-thick alu-minium plate. A total of 100,000 counts were acquired from a 170 MBq line source established in a capillary tube ($\emptyset_{\text{inner}} = 1.15 \text{ mm}, \emptyset_{\text{outer}} = 1.50 \text{ mm}, L = 75 \text{ mm}$). 181 Intrinsic flood field uniformity

The intrinsic uniformity quantifies the γ -camera's response to a uniform radiation flux. An 8 MBq point source was centered 65 cm above the face of the detector and 100 million counts were acquired. The measured and simulated flood field projection images with 1 mm pixels were smoothed once by convolution with the NEMA smoothing filter, and measured data were corrected for uniformity. The integral uniformity was calculated using

Uniformity (%) =
$$\frac{\text{max} - \text{min}}{\text{max} + \text{min}} \times 100$$
 (2)

where max and min refer to the maximum and minimum pixel values within the FOV. Similarly, the differential uniformity was calculated with Eq. 2 from the max and min in a set of five contiguous pixels in a row or column.

Multiple window spatial registration

The multiple window spatial registration (MWSR) test was performed with 11 MBq of ⁶⁷Ga to assess the Spark's ability to accurately localize photons of different en-ergies when imaged through different energy windows. The previously described pencil beam source holder (see Intrinsic spatial resolution and linearity) was posi-tioned in a 1.0 cm-thick aluminium plate at nine locations along the detector axes, including the center of the detector, $0.4\times$, and $0.8\times$ the distance to the edge of the UFOV. A total of 4 million counts were acquired at each position, and projection images were generated from each photopeak. The maximum axial and transaxial displacements of PSF centroids were then calculated. Overall spatial registration accuracy was also assessed according to the mean Euclidean distance between each centroid and the average centroid location.

204 Intrinsic count rate performance in air: Decaying source method

The count rate performance describes the γ -camera's ability to process one detec-

tion event before moving on to another. However, the number of recorded counts
may be fewer than true events because of dead time and/or pile-up. Two models
exist to describe idealized dead time behaviour: paralyzable and non-paralyzable
dead time [25]. The Spark's behaviour is well-described with a paralyzable model
following the equation

OCR = ICR
$$e^{-OCR\tau}$$
 (3)

where OCR is the observed count rate, ICR is the input count rate, and τ is the system dead time. Furthermore, OCR can be affected by pile-up, which occurs when a true event at time t=0 is followed by subsequent events in the interval $0 < t < \tau$, followed by an event-free interval of length τ . Using the decaying source method, the dead time was calculated from the intercept and slope of Eq. 4:

$$\lambda t + \ln OCR = -ICR_0 \tau e^{-\lambda t} + \ln ICR_0 \tag{4}$$

where λ is the decay constant, t is the time, ICR₀ is the true input rate at the beginning of measurement, $e^{-\lambda t}$ is the abscissa, and $\lambda t + \ln OCR$ is the ordinate [25]. Care was taken to minimize scatter during count rate performance assessment by securing an Eppendorf tube containing 235 MBq in a tungsten Capintec 511 Dose Drawing Syringe Shield. The shield was capped with a lead lid, and a 6.0 mm-thick copper plate covered the open side of the source holder. The source was placed at a distance of 5×UFOV above the detector face to produce a uniform radiation field. Counts were measured for 60 s and simulated for 10 s in 60 min intervals, and the last data point was acquired when the observed count rate dropped below 600 cps to determine ICR₀ accurately. All data were corrected for radioactive decay, and the measured data were corrected for background noise and uniformity. Measured count rate data were utilized to configure the digitizer's pile-up, dead time, and efficiency modules. Following the NEMA protocol, the intrinsic count rate performance was analyzed in terms of the maximum OCR and 20% loss OCR.

232 Intrinsic energy resolution

The energy resolution characterizes a radiation detector's response to a monoenergetic radiation source and describes its ability to distinguish between different energies of that radiation. The formal definition is

Energy resolution (%) =
$$\frac{\text{FWHM}}{\text{Photopeak location}} \times 100$$
 (5)

where FWHM is the full width at half maximum of the photopeak calculated according to NEMA's resolution methodology in this context. The Spark's intrinsic energy resolution was assessed using 0.6 keV bins with the count rate data point immediately below the 20% loss OCR introduced in the previous section (Intrinsic count rate performance in air: Decaying source method). This data point satisfies all NEMA conditions while offering count rate traceability. The simulated data point below the 20% loss OCR was re-simulated with a 60 s acquisition time to obtain count statistics comparable to the measurement. Note that a keV-per-channel calibration factor was not calculated with cobalt-57 (⁵⁷Co) since a vendor-specific energy calibration is automatically applied to list mode data.

Tests of gamma camera detectors with collimators

In this study, system or *extrinsic* measurements primarily involved the SPH collimator due to its applicability in planar scintigraphy yielding unambiguous projection images. Measurements with the experimental MPH were included where applicable.

System spatial resolution without scatter

The system spatial resolution without scatter represents the γ -camera's limiting ability to localize a photon interaction site in the detector when combin-

ing collimator and intrinsic factors. Acquisitions were performed in the axial and transaxial directions using a precision capillary tube ($\varnothing_{inner} = 0.4 \text{ mm}$, $\varnothing_{outer} = 0.8 \text{ mm}$, L = 75 mm). The capillary tube contained 10 MBq of radioactivity, and 100,000 counts were acquired at positions of $\{0.4, 25.0, 50.0, 75.0, \text{ and } 100.0\}$ mm from the face of the SPH collimator. NEMA's resolution methodology was applied to calculate resolution from LSFs. Results were corrected for magnification to compare resolution in the object rather than the detector. A plot of the average system resolution as a function of source-to-collimator distance was generated with a linear least squares fit to characterize the system resolution.

263 System spatial resolution with scatter

The presence of a scattering medium degrades image quality in terms of projection image blurring, reduced contrast in reconstructed images, and decreased quantita-tive accuracy [26]. Thus, the system spatial resolution with scatter was assessed with a custom mouse phantom inspired by the NEMA NU 1-2018 standard and the micro-PET scatter phantom defined in the NEMA NU 4-2008 standard for preclin-ical PET [27]. The custom mouse phantom was fabricated from an acrylic cylinder $(\varnothing = 25.4 \text{ mm}, L = 60 \text{ mm})$ with three 0.8 mm-diameter bores for precision capil-lary tubes: one at the center and two separated by 90° with a 10 mm radial offset. One precision capillary tube containing 10 MBq was inserted into the central bore of the custom phantom, and 100,000 counts were acquired axially and transaxially at capillary tube positions of {12.7, 25.0, 50.0, 75.0, and 100.0} mm from the face of the collimator. Analysis of the resulting projection images was identical to the methods outlined in System spatial resolution without scatter.

277 System planar sensitivity

The system planar sensitivity characterizes the number of detected counts per unit activity to evaluate a collimator's count rate performance. A petri dish with a 35.0 mm diameter was filled with 2 ml of water and injected with a calibrated activ-

ity of $A_{\rm cal}=210$ MBq for the SPH dataset and $A_{\rm cal}=25$ MBq for the MPH dataset.

The internal base of the radioactive solution was placed at source-to-collimator distances of $D=\{10.0,\,20.0,\,28.0,\,50.0,\,$ and $100.0\}$ mm, and 4 million counts were collected at each position in measurement. In contrast, counts were collected for 100 s at each position in simulation to save on computing time. Data were acquired from the largest to the smallest distance with activity levels ranging from $A_{\rm cal}$ to ~ 15 MBq to minimize pile-up and dead time effects, namely in the SPH acquisition.

Measured data were corrected for uniformity, and then the decay-corrected count rate R was calculated for each acquisition i as

$$R_i = \lambda C_i e^{\lambda (T_i - T_{\text{cal}})} \times \left(1 - e^{-\lambda T_{\text{acq},i}}\right)^{-1}$$
(6)

where C_i is the summed counts from the projection image, T_i is the acquisition start time, $T_{\text{acq},i}$ is the acquisition duration, and T_{cal} is the time of activity calibration. Using a standard Levenberg-Marquardt non-linear least squares fit technique, the decay-corrected count rate and source-to-collimator distance for each SPH acquisition were fit with the function

$$R_i = c_0 + c_1 e^{(-c_2 D_i)} (7)$$

where c_0 , c_1 , and c_2 are fitting parameters. The total system sensitivity $S_{\rm TOT}$ was then calculated as

$$S_{\text{TOT},i} = \frac{R_i}{A_{\text{cal}}} \tag{8}$$

and plotted against the source-to-collimator distance to characterize the sensitivity.

Note that NEMA's protocol utilizes fit parameters from Eq. 7 to compute a collimator tor penetration factor for counts in a given region of interest (ROI). This analysis

was excluded as it does not apply to pinhole collimators. Furthermore, Eq. 7 does not apply to the MPH collimator due to the focusing orientation of pinholes.

305 Tests specific to tomographic camera systems

SPECT projection data were acquired from 0° to 270° in a 208×208 matrix with 0.5 mm isotropic pixels, then reconstructed with nine iterations of the maximum likelihood expectation maximization (MLEM) algorithm in 0.25 mm isotropic voxels. SPH SPECT data were acquired in 3° increments then reconstructed with STIR in a 230×184×184 matrix, and MPH SPECT data were acquired in 90° increments then reconstructed with HiSPECT in an 80×144×144 matrix. HiSPECT software only supports the MLEM algorithm, whereas STIR's pinhole-SPECT software per-mits access to STIR's extensive library of algorithms and corrections for the spatially variant collimator-detector response and attenuation. Thus, SPH SPECT data were also reconstructed with the filtered back projection (FBP) algorithm using a ramp filter to adhere to the NEMA protocol.

SPECT reconstructed spatial resolution without scatter

The reconstructed spatial resolution without scatter reflects the limiting size of a radioactive distribution that can be observed with the γ -camera. Three point sources in air were established in precision capillary tubes with a mean activity of 0.274 ± 0.007 MBq and an axial extent of ~ 0.4 mm. To conform to the small recon-structed FOV of the MPH collimator (see Table 1), one point source was centered on the axis of rotation, and the two remaining point sources were positioned at $\pm 75\%$ of the distance to the edge of the FOV, i.e., ± 5.25 mm axially and ± 11.25 mm transaxially. The point sources were set in place, and 300,000 counts were acquired across all projections in the SPH and MPH acquisitions to directly compare to-mographic resolution. Cubic ROIs were centered around each reconstructed point source and summed along each axis to calculate the radial, tangential, and axial resolution without scatter according to the NEMA protocol.

The reconstructed spatial resolution with scatter was assessed with the custom mouse phantom described in System spatial resolution with scatter. Three capillary tubes containing a mean activity of 9.4 ± 0.1 MBq were inserted into the phantom and centered axially in the FOV with peripheral line sources placed at 0° and 270° to maximize the amount of scatter contributing to projection images over the extent of rotation. The line sources in the custom mouse phantom were set in place, and 5 million counts were acquired across all projections in the SPH and MPH

SPECT reconstructed spatial resolution with scatter

and 5 million counts were acquired across all projections in the SPH and MPH acquisitions to directly compare tomographic resolution. The reconstructed images were summed axially to obtain three 3.5 mm-thick transverse slices: one at the center of the FOV and two at $\pm 75\%$ the distance to the edge of the respective axial FOV. A square ROI was centered on each resulting PSF to calculate the central, radial, and tangential resolution with scatter according to the NEMA protocol.

343 SPECT volume sensitivity and uniformity

The system volume sensitivity (SVS) reports the total system sensitivity to a uniform activity concentration in a cylindrical phantom. An acrylic phantom ($\varnothing_{\rm inner}=26~{\rm mm},~\varnothing_{\rm outer}=28~{\rm mm},~L_{\rm inner}=21~{\rm mm}$) was filled with water containing 1.75 MBq/ml then centered along the axis of rotation in the γ -camera's image space. The phantom was set in place, and SPH and MPH SPECT acquisitions were obtained with 10 s and 60 s projections, respectively. The measured data were corrected for uniformity, and then the SVS was calculated as

$$SVS = \frac{A}{B_c}$$
 (9)

where A is the average count rate (total counts divided by total elapsed time including time for rotation) and B_c is the activity concentration halfway through the acquisition. By normalizing the SVS by the axial extent L of the cylindrical phantom in the reconstructed image, the volume sensitivity per axial centimeter (VSAC)
was calculated as

VSAC =
$$\frac{\text{SVS}}{L}$$
. (10)

The VSAC was then multiplied by the reconstructed axial FOV of the collimator to obtain a useful approximation of the total system response to a broad distribution of radioactivity.

Although it is not a defined NEMA test, the volume uniformity was evaluated from images of the cylindrical phantom reconstructed with the MLEM algorithm.

Integral uniformity was calculated with Eq. 2 from a VOI covering 75% of the phantom's imaged length and 60% of the phantom's inner diameter. Within this VOI, the root-mean-square (RMS) noise was also calculated as

RMS noise (%) =
$$\frac{\sigma}{\mu} \times 100$$
 (11)

where σ is the standard deviation and μ is the mean voxel value within the VOI [28].

368 Results

369 Tests of intrinsic gamma camera detector characteristics

370 Intrinsic spatial resolution and linearity

Representative planar mask projection images from measured and simulated acquisitions are presented in Fig. 3, and Table 2 gives the intrinsic spatial resolution determined from the pencil beam PSF and planar mask LSFs in terms of the FWHM and full width at tenth maximum (FWTM). The pencil beam produced a measured and simulated limiting intrinsic spatial resolution of 0.85 mm, which was \sim 7% below that predicted by the planar mask slits. Table 2 also presents the differential and absolute intrinsic spatial linearity results, which were found to be \lesssim 0.1 mm in measured

surement and simulation. The measured and simulated linearity results calculated a calibration factor of 0.099 mm/pixel. Altogether, good agreement was observed between measurement and simulation, and measured results indicated highly accurate positioning and minimal distortion of detected photons with the SiPM array.

 $_{382}$ \rightarrow Figure 3 goes here.

Table 2 Intrinsic spatial resolution and linearity.

Reporting parameter	Region of interest	Measurement	Simulation
Resolution PSF FWHM (mm)	Center of FOV	0.851 ± 0.010	0.850 ± 0.003
Resolution PSF FWTM (mm)	Center of FOV	1.559 ± 0.014	1.591 ± 0.007
Resolution LSF FWHM (mm)	UFOV	0.912 ± 0.098	0.916 ± 0.026
	CFOV	0.953 ± 0.091	0.924 ± 0.029
Resolution LSF FWTM (mm)	UFOV	1.73 ± 0.15	1.66 ± 0.03
• • •	CFOV	1.80 ± 0.14	1.68 ± 0.03
Differential linearity (mm)	UFOV	0.023	0.001
	CFOV	0.024	0.002
Absolute linearity (mm)	UFOV	0.102	0.003
	CFOV	0.055	0.003

383 Intrinsic flood field uniformity

Integral and differential uniformity calculated from the UFOV and CFOV of flood field images are presented in Table 3. The measured and simulated uniformity results were < 3% and < 2%, respectively, showing good agreement and uniform response to radiation.

Table 3 Flood field uniformity.

Reporting parameter	Region of interest	Measurement	Simulation
Integral uniformity (%)	UFOV	2.96	1.72
	CFOV	2.79	1.96
Row differential uniformity (%)	UFOV	2.75	1.69
	CFOV	2.52	1.77
Column differential uniformity (%)	UFOV	2.75	1.67
	CFOV	2.11	1.67

388 Multiple window spatial registration

The higher energy γ -rays from 67 Ga were observed to penetrate the walls of the tungsten pencil beam holder and produce noisy projection images, resulting in a significant fraction of total counts detected outside the pencil beam PSF. Nonetheless, the measured (simulated) MWSR was found to have maximum PSF centroid displacements in the axial and transaxial directions of 0.192 mm (0.095 mm) and 0.259 mm (0.149 mm), respectively, which reflects the worst-case-scenarios of mis-

registration. The mean Euclidean distance between each centroid and the average centroid location for a given pencil beam location was 0.050 ± 0.023 mm and 0.044 ± 0.022 mm in measurement and simulation, respectively. In other words, photons of different energies were accurately localized, and centroids from different energy windows were found within one pixel of each other on average.

Intrinsic count rate performance in air: Decaying source method Figure 4 presents the 99m Tc count rate performance curve where the measured (simulated) maximum and 20% loss OCRs were 15,410 cps (15,500 cps) and 7.520 (7.440 cps), respectively. The measured data were corrected for uniformity and a background count rate of 11.6 cps to directly compare with the simulation for which no corrections were necessary. The measured and simulated results were comparable at input count rates below the maximum. However, the experimental detector did not behave like an idealized paralyzable system at relatively large count rates. Unexpected behaviour was observed through photopeak shifting in addition to pulse pile-up and dead time effects at count rates beyond the maximum — a count rate range unlikely to be encountered with typical in vivo usage of the Spark. The measured (simulated) dead time was found to be 23.9 μ s (23.8 μ s) using Eq. 4. \rightarrow Figure 4 goes here.

413 Intrinsic energy resolution

Energy spectra are presented in Fig. 5 where the intrinsic energy resolution was 14.7% in measurement and simulation. Minute differences can be observed in the energy spectra at energies above the photopeak due to incomplete scintillation light collection during pile-up in the experimental system. Aside from the differences in pile-up energy distribution, a 3.1% difference was found in the number of pile-up events detected in an energy window extending above 150 keV.

 $_{120}$ \rightarrow Figure 5 goes here.

Tests of gamma camera detectors with collimators

- System spatial resolution without scatter
- 423 The system spatial resolution without scatter is shown in Fig. 6. A linear least
- 424 squares fit to the measured and simulated data calculated a coefficient of determina-
- tion of $r^2 = 1.0$ and similar FWHM line equations. The FWHM equations predicted
- a measured (simulated) limiting system spatial resolution of 1.87 mm (1.80 mm)
- 427 at the center of rotation (D = 23.0 mm). Overall, the FWHM differences between
- measurement and simulation varied from 4.8% to 3.2% over source-to-collimator
- distances from 0 mm to 100 mm, respectively. A discrepancy can be observed in
- the FWTM best-fit lines.
- \rightarrow Figure 6 goes here.
- System spatial resolution with scatter
- 433 The system spatial resolution with scatter in the custom mouse phantom is pre-
- sented in Fig. 7. Linear least squares fits calculated a coefficient of determination of
- $r^2 = 1.0$ and comparable FWHM and FWTM fit equations between measurement
- and simulation. The FWHM equations predicted a measured (simulated) system
- spatial resolution with scatter of 1.98 mm (1.88 mm) at the center of rotation. Here,
- the FWHM differences between measurement and simulation varied from 7.1% to
- 2.9% over source-to-collimator distances from 0 mm to 100 mm, respectively. Inter-
- estingly, the FWTM best-fit lines have a higher degree of correspondence between
- measurement and simulation with scatter than without.
- \rightarrow Figure 7 goes here.
- 3 System planar sensitivity
- The total system planar sensitivity is presented in Fig. 8 for the SPH and MPH
- collimators. For the SPH collimator, the exponential fit calculated a measured (sim-
- ulated) planar sensitivity of 33.8 cps/MBq (35.2 cps/MBq) at the center of rotation,
- reflecting a 4.0% difference. The difference increased to 14.2% at the face of the col-

limator, which could be partly due to limitations in modelling the collimator with a 0.85 mm pinhole. For the MPH collimator, sensitivity is optimized within the tomographic FOV due to the focusing nature of the pinholes. Therefore, the three largest values were fit with a quadratic function, and interpolation at the center of rotation calculated a planar sensitivity of 150 cps/MBq.

 \rightarrow Figure 8 goes here.

454 Tests specific to tomographic camera systems

455 SPECT reconstructed spatial resolution without scatter

Table 4 details the three-dimensional (3D) resolution results from all reconstructed point source images. Acquisitions with the SPH collimator calculated a measured (simulated) limiting 3D resolution of 1.37 ± 0.15 mm (1.30 ± 0.15 mm). The MPH collimator yielded a 13% improvement in the limiting 3D resolution with a value of 1.19 ± 0.20 mm and a submillimeter tangential resolution (0.91 \pm 0.05 mm) due to the lateral focusing pinholes. Note that leaching of radioactivity into the capillary tube sealing clay was observed in measured tomographic images. A closer inspection of Table 4 confirms that the axial resolutions were overestimated in measurement when considering that all other FWHM were nearly identical between SPH collimator measurement and simulation.

Table 4 SPECT reconstructed spatial resolution without scatter.

Reporting parameter	Measurement			Simulation	
Collimator	MPH	SPH	SPH	SPH	SPH
Reconstruction algorithm	MLEM	MLEM	FBP	MLEM	FBP
Central transaxial FWHM (x,y) (mm)	1.29 ± 0.04	1.45 ± 0.01	2.26 ± 0.01	1.50 ± 0.01	2.26 ± 0.01
Central axial (mm)	1.56 ± 0.01	1.58 ± 0.01	2.45 ± 0.01	1.31 ± 0.01	2.26 ± 0.01
Peripheral radial FWHM (x) (mm)	1.13 ± 0.08	1.25 ± 0.06	2.03 ± 0.10	1.30 ± 0.09	2.11 ± 0.25
Peripheral tangential FWHM (y) (mm)	0.91 ± 0.05	1.23 ± 0.11	1.94 ± 0.14	1.26 ± 0.13	1.93 ± 0.10
Peripheral axial FWHM (z) (mm)	1.24 ± 0.04	1.45 ± 0.16	2.70 ± 0.04	1.12 ± 0.06	2.48 ± 0.05
Average 3D ` FWHM (mm)	1.19 ± 0.20	1.37 ± 0.15	2.26 ± 0.30	1.30 ± 0.15	2.20 ± 0.23

SPECT reconstructed spatial resolution with scatter

Figure 9 presents the central 3.5 mm-thick slice of the custom mouse phantom from the MLEM reconstructions, and Table 5 gives a breakdown of the in-plane resolution values from all reconstructed mouse phantom images. Acquisitions with the SPH collimator produced a measured (simulated) average in-plane resolution of 1.44 ± 0.07 mm (1.46 ± 0.07 mm), and the MPH collimator yielded a 17% improve-ment with an average FWHM of 1.18 ± 0.15 mm. Measurement and simulation were found to have an excellent agreement in tomographic resolution with differences be-low 2%. Although the MPH collimator is capable of higher resolution than the SPH collimator, the reduced standard deviation of the SPH resolution indicates that its in-plane resolution is more symmetric throughout the tomographic FOV.

ightarrow Figure 9 goes here.

Table 5 SPECT reconstructed spatial resolution with scatter.

Reporting parameter	Measurement			Simulation	
Collimator	MPH	SPH	SPH	SPH	SPH
Reconstruction algorithm	MLEM	MLEM	FBP	MLEM	FBP
Central FWHM (mm)	1.29 ± 0.05	1.52 ± 0.04	2.23 ± 0.07	1.54 ± 0.05	2.21 ± 0.08
Radial FWHM (mm)	1.27 ± 0.06	1.39 ± 0.06	2.34 ± 0.11	1.40 ± 0.04	2.30 ± 0.06
Tangential FWHM (mm)	0.99 ± 0.07	1.41 ± 0.03	2.03 ± 0.11	1.43 ± 0.03	2.06 ± 0.10
Average in-plane FWHM (mm)	1.18 ± 0.15	1.44 ± 0.07	2.20 ± 0.16	1.46 ± 0.07	2.19 ± 0.12

478 SPECT volume sensitivity and uniformity

Tomographic images of the cylindrical phantom reconstructed with the MLEM algorithm are presented in Fig. 10, and the corresponding volume sensitivity, uniformity, and RMS noise results are given in Table 6. When comparing the measurement to simulation, the SPH volume sensitivity had the largest discrepancy observed across all NEMA tests, with a difference of 7.3%. This can be attributed to the slight overestimation in simulated sensitivity and an air bubble in the phantom during measurement that increased the source-to-collimator distance on average.

Although the SPH collimator has fewer pinholes than the MPH collimator and uti-

lizes a smaller area of the UFOV, its increased tomographic FOV and total system
response compensate for the relatively low sensitivity. Furthermore, tomographic
images produced with the SPH collimator are significantly more uniform and less
noisy than those made with the MPH collimator.

$_{ exttt{491}}$ ightarrow Figure 10 goes here.

Table 6 SPECT volume sensitivity and uniformity.

Reporting parameter	Measu	rement	Simulation
Collimator	MPH	SPH	SPH
SVS (cps/(MBq/cm ³))	2,200	329	354
VSAC (cps/(MBq/cm ²))	1,570	157	169
Total system response (cps/(MBq/cm ³))	2,200	901	970
Integral uniformity (%)	96.5	48.2	38.2
RMS noise (%)	38.7	11.6	10.2

Discussion

The performance characteristics of a high-resolution SiPM-based preclinical SPECT system — the Cubresa Spark — have been evaluated for the first time according to the NEMA NU 1-2018 Standard for Performance Measurements of Gamma Cameras. The primary challenge in applying the NEMA NU 1 standard in a preclinical setting with a small-area detector was satisfying count-related specifications in the MWSR and SPECT reconstructed spatial resolution tests. For these tests, practical count-deprived acquisitions were obtained in favour of timely measurements as adherence to count criteria was inherently so time-consuming that it was considered unduly burdensome. One test that exceeded the count criteria was the intrinsic count rate performance in air which specifies that the final data point should be measured when the observed count rate drops below 4,000 cps because the dead time is only a fraction of a percent. Adherence to this specification would have yielded an overestimated 20% loss count rate of 10,000 cps due to a failure to extract the true input count rate from the linear response region of the detector. Upon comparison with available reference values from Cubresa, the measured intrinsic spatial resolution of 0.851 ± 0.010 mm was in excellent agreement with the reference value of 0.85 mm. To our knowledge, this is the highest reported intrinsic

resolution of any γ -camera evaluated with the NEMA NU 1 standard to date. When comparing the system sensitivities, measured results of 33.8 cps/MBq for the SPH collimator and 150 cps/MBq for the MPH collimator were not in agreement with the respective reference values of 50 cps/MBq and 467 cps/MBq. Instead, Cubresa's reference sensitivities appear to relate to the overall console count rate before data processing, which can be understood as follows: As the input count rate increases linearly, the overall console count rate also increases proportionally, but the observed count rate does not. In the linear region of the count rate performance curve at low input count rates, the overall console count rate was approximately 1.65× greater than the observed count rate. However, it increased exponentially to $3.81\times$ at the maximum observed count rate. This range of multiplicative factors is consistent with Cubresa's reference sensitivities when applied to the NEMA sensitivity results.

When comparing internal results between measurement and simulation, the intrin-sic performance parameters were very similar, and measured results were accurately simulated, which primarily validates the GATE detector head and digitizer settings. The parameters set in the digitizer differ from the corresponding observables, high-lighting the importance of tuning the digitizer — a complex achievement with the Spark since it is not a conventional γ -camera. This process was made simpler and more accurate by applying NEMA's methodology. Comparisons of the system and SPECT performance also showed excellent agreement between measurement and simulation, with the most considerable differences amounting to $\lesssim 7\%$. Altogether, these results confirm the accuracy of the Monte Carlo simulation results and satisfy the secondary objective of validating the GATE simulation model of the Spark for future use in preclinical SPECT studies, such as validating STIR's forthcoming pinhole-SPECT image reconstruction capabilities.

When tuning the GATE model for the system and tomographic simulations, a 0.85 mm pinhole diameter was defined for the SPH collimator to better match

the measured and simulated collimator-detector response functions in terms of resolution and sensitivity. Using a 1.0 mm-diameter pinhole, the simulated system resolution without scatter was characterized as FWHM = 0.0424D + 1.12 (mm), which agrees well with theoretical equations from Van Audenhaege et al. [29], but predicts a limiting resolution of 2.10 mm at the center of rotation that does not correspond with the measured result of 1.87 mm. This discrepancy can be attributed to a vendor-specific event positioning algorithm that improves the Spark's resolution, which could not be accounted for using the digitizer. Similarly, the sim-ulated 1.0 mm pinhole system planar sensitivity was characterized as S_{TOT} = $4.33 + 148e^{(-0.0563D)}$ (cps/MBq), which predicts a sensitivity of 44.9 cps/MBq at the center of rotation which is much greater than the measured result of 33.8 cps/Mbq. This discrepancy could relate to the choice of G4 CESIUM IODIDE as the scintillator material from the Geant4 database. This predefined material describes unactivated CsI and has the same physical characteristics as CsI(Na) and thallium-activated CsI (CsI(Tl)), but differs in terms of optical properties such as scintillation light yield, de-excitation time, refractive index, and peak emission wavelength [30, 31]. The introduction of optical properties into the simulation could allow for simulation of the entire SiPM readout logic to improve sensitivity and overall simulation accuracy. However, it would significantly increase computation time. Current efforts are ongoing to incorporate SiPM-specific software into GATE's digitizer to reproduce signals from SiPMs [32, 33].

Several commercially available preclinical SPECT systems have been validated with GATE using ^{99m}Tc and are compared in Table 7. Comparisons with pinhole collimators are made against 1.0 mm-diameter pinholes where data were available except for the NanoSPECT/CT^{PLUS} which uses 1.5 mm pinholes. System and SPECT parameters are cited at the radius of rotation. These tabulated studies not only demonstrate the flexibility and reliability of GATE for accurately modelling

various detector designs but also illustrate the potential of SiPMs in molecular imaging. Comparisons of γ -camera performance for different imaging systems are best performed according to the NEMA NU 1 standard as it provides a uniform and consistent method for measuring and reporting performance parameters for various camera designs. Unfortunately, most tabulated systems were not evaluated with NEMA standards, perhaps due to the absence of a dedicated preclinical SPECT standard from NEMA, a shortage of required resources, or a restriction from es-sential scanner data. Therefore, direct comparisons are limited due to inconsistent reporting parameters from different researchers and organizations. Nonetheless, this study has demonstrated competitive performance characteristics of the novel SiPM-based SPECT system, including the highest intrinsic spatial resolution of the tabu-lated γ -cameras, the smallest form factor, good energy resolution, and comparable sensitivity and tomographic resolution to the top-performing preclinical systems.

Table 7 Performance characteristic comparisons of commercial preclinical SPECT cameras validated with GATE.

Reporting parameter	Spark	X-SPECT	Inveon	HiReSPECT	NanoSPECT
Detection method	SiPM	CZT	PSPMT	PSPMT	PMT
Scintillator ^[3]	CsI(Na)	N/A	Nal(Tl)	CsI(Na)	Nal(Tl)
$Collimator^{[4]}$	SPH/MPH	SPH/MPH	SPH/MPH	PH	SPH/MPH
Radius of rotation (mm)	28	25	25	25	45
Magnification factor	\sim 1 \times	\sim 4 \times	\sim 4 \times	$1 \times$	~3.5×
Intrinsic spatial resolution (mm)	0.85	1.5	N/A	N/A	3.2
Intrinsic energy resolution (%)	14.7	5	12.4	19.15	9.7
System resolution (mm)	SPH: 1.87	SPH: 1.02	N/A	2.79	N/A
Sensitivity `	SPH: 34	MPH: 155	SPH: 38	36 - 42	SPH: 42
(cps/MBq)	MPH: 150		MPH: 286		MPH: 191
SPECT	SPH: 1.37	MPH: 0.58	SPH: 1.25	1.7	SPH: 1.27
resolution (mm)	MPH: 1.19				MPH: 1.24
References	N/A	[9, 34, 35]	[10, 36, 37]	[11, 38, 39]	[12]

^[3]SPH: Single-pinhole, MPH: Multi-pinhole, PH: Parallel-hole

77 Conclusion

The performance of a novel, preclinical SiPM-based SPECT scanner has been characterized according to the NEMA NU 1-2018 Standard for Performance Measurements of Gamma Cameras. Measured and simulated NEMA tests were highly com-

^[4]CsI(Na): Sodium-activated cesium iodide, NaI(TI): Thallium-activated sodium iodide N/A: Not applicable or not available

parable, where the most considerable differences were below 7%, and overall differences were a few percent. This confirms simulation accuracy and satisfies the
secondary objective of validating the GATE Monte Carlo model. The multi-pinhole
collimator investigated in this study offers the optimal combination of spatial resolution and sensitivity for organ-specific imaging of small animals, and the singlepinhole collimator enables high-resolution whole-body imaging of small animals.
This work demonstrates that a SiPM detector mitigates the need for highly magnifying collimators while preserving detailed information in projection images.

Declarations

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598 Abbreviations

- 3D: Three-dimensional; ⁵⁷Co: Cobalt-57; ⁶⁷Ga: Gallium-67; ⁹⁹mTc: Technetium-99m; Csl(Na):
- 600 Sodium-activated cesium iodide; CsI(TI): Thallium-activated cesium iodide; CT: computed tomography; CZT:
- 601 Cadmium zinc telluride; EGS: Electron Gamma Shower; FBP: Filtered back projection; FOV: Field of view;
- 602 FWHM: Full width at half maximum; FWTM: Full width at tenth maximum; GATE: Geant4 Application for
- 603 Tomographic Emission; Geant4: Geometry and Tracking; ICR: Input count rate; LSF: Line spread functions;
- 604 Meas: Measurement; MLEM: Maximum likelihood expectation maximization; MCNP: Monte Carlo N-Particle;
- 605 MPH: Multi-pinhole; MWSR: Multiple window spatial registration; Nal(TI): Thallium-activated sodium iodide;
- 606 NEMA: National Electrical Manufacturers Association; OCR: Observed count rate; PET: Positron emission
- tomography; PH: Parallel-hole; PMT: Photomultiplier tube; PSF: Point spread function; PSPMT: Position
- 608 sensitive photomultiplier tube; RMS: Root-mean-square; ROI: Region of interest; Sim: Simulation; ROOT:
- 609 Rapid Objected-Oriented Technology; SiPM: Silicon-photomultiplier; SPECT: Single-photon emission computed
- 610 tomography; SPH: Single-pinhole; STIR: Software for Tomographic Image Reconstruction; STL: Standard
- 611 tessellation language; SVS: System volume sensitivity; UFOV: Useful field of view; VOI: Volume of interest;
- VSAC: Volume sensitivity per axial centimeter.

613 Availability of data and materials

- The datasets used and/or analyzed during the current study are available from the corresponding author on
- 615 reasonable request.

- 616 Ethics approval and consent to participate
- 617 Not applicable.
- 618 Competing interests
- 619 The Biomedical Translational Imaging Centre and Cubresa share an academic-industry research collaboration.
- 620 Consent for publication
- 621 Not applicable.
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- 623 MS performed data collection and analysis and wrote the manuscript. DD, SB, and KB contributed to the
- 624 conceptualization and review of the study. All authors contributed to the revision of the manuscript and read
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761 Figures

Manufacturer's model GATE model

Figure 1 The Spark preclinical SPECT scanner illustrated in a cutaway side view of the manufacturer's model (left) and GATE model (right). Only the detector head and single-pinhole collimator were included in the Monte Carlo model.

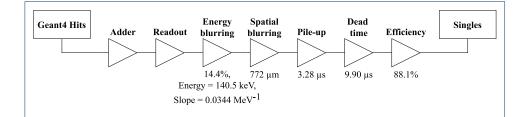


Figure 2 Digitizer signal processing model of the Spark's readout electronics used in GATE. Interactions in the scintillator were recorded as hits following Geant4 particle generation and transport through modelled materials. Hits were subsequently filtered through the digitizer modules to obtain singles corresponding to the detected signal after processing by the front-end electronics.

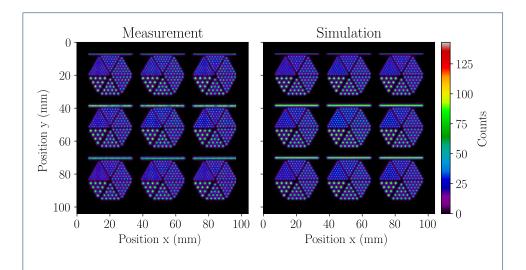


Figure 3 Representative planar mask projection images from measurement (left) and simulation (right) with 0.1 mm isotropic pixels and without uniformity correction. The measured image agrees well with the simulation and demonstrates the minimal distortion and superior resolution of SiPMs. The Derenzo patterns are fully resolved, and the FWHM of PSFs produced by the 0.7 mm diameter holes were consistent with a limiting intrinsic resolution of 0.85 mm. The central line profiles were placed across the center of the detector to calculate intrinsic resolution and linearity, thereby cropping the Derenzo pattern.

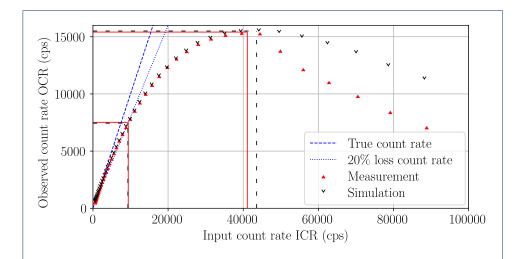


Figure 4 Intrinsic count rate performance in air. Measured results are shown with red solid carets and simulated results with black empty carets. Additional lines illustrate the maximum OCR and 20% loss OCR for measurement (solid lines) and simulation (dashed lines). The count rates are in agreement below the maximum OCR while above the maximum, the measured OCR falls off the trend line as the photopeak shifted to lower energies.

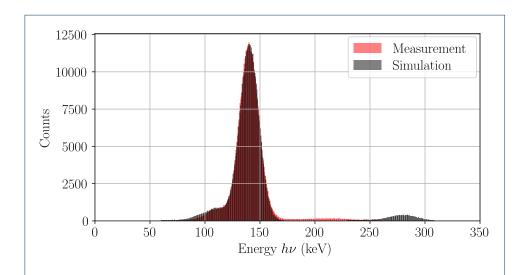


Figure 5 Measured and simulated ^{99m}Tc energy spectra acquired at a count rate loss below 20%. The intrinsic resolution was 14.7% in both cases. Differences can be observed in the pile-up energy distribution due to partial scintillation light collection of the SiPM array, which was not modelled with GATE.

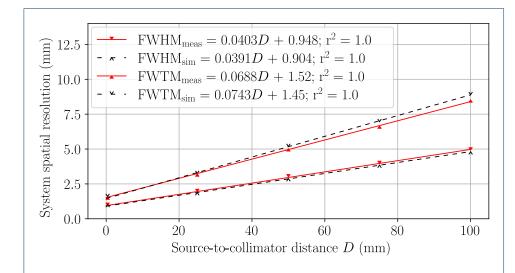


Figure 6 System spatial resolution without scatter presented in terms of FWHM and FWTM for the SPH collimator. Measured results are shown with solid red carets and solid lines of best fit, and simulated results are shown with empty black carets and dashed lines of best fit. Equations for lines of best fit are distinguished in the legend with abbreviated subscripts. The measured (simulated) system resolution without scatter at the center of rotation was 1.87 mm (1.80 mm).

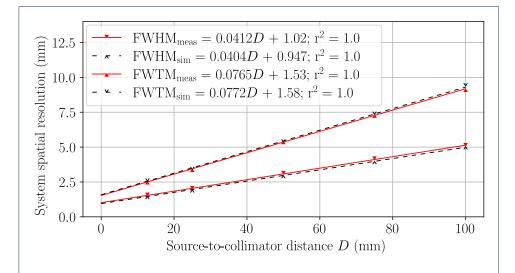


Figure 7 System spatial resolution with scatter in a custom mouse phantom presented in terms of FWHM and FWTM for the SPH collimator. Measured results are shown with solid red carets and solid lines of best fit, and simulated results are shown with empty black carets and dashed lines of best fit. Equations for lines of best fit are distinguished in the legend with abbreviated subscripts. The measured (simulated) system resolution with scatter at the center of rotation was 1.97 mm (1.88 mm).

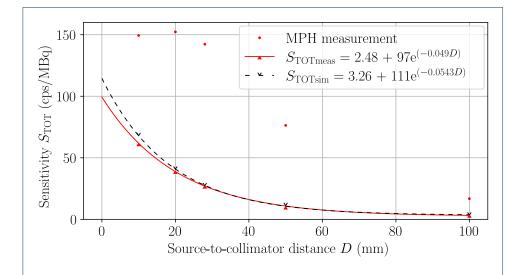


Figure 8 Planar sensitivity as a function of source-to-collimator distance. For the SPH collimator, measured results are shown with solid red carets, and a solid line of best fit and simulated results are shown with black with empty carets and a dashed line of best fit. MPH collimator results are shown as red dots. Fit equations for the SPH collimator measurement and simulation are distinguished in the legend with abbreviated subscripts. The MPH collimator geometry is optimized for increased sensitivity in the tomographic FOV, whereas the SPH collimator sensitivity increases when approaching the pinhole.

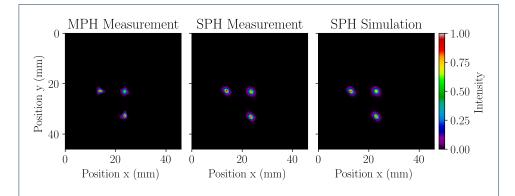


Figure 9 SPECT reconstructed spatial resolution with scatter evaluated with a custom mouse phantom in MPH collimator measurement (left), SPH collimator measurement (middle), and SPH collimator simulation (right). The images present the central 3.5 mm-thick transverse slice used in calculating the radial, tangential, and central resolution. The MPH collimator offers superior tomographic resolution compared to the SPH collimator when scanning relatively small radioactivity distributions.

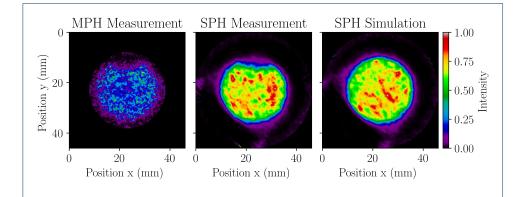


Figure 10 SPECT volume sensitivity and uniformity evaluated with a cylindrical phantom in MPH collimator measurement (left), SPH collimator measurement (middle), and SPH collimator simulation (right). The images present the central 0.25 mm-thick transverse slice used in calculating volume uniformity and RMS noise. A bubble can be seen in the measured data that was not modelled in the simulation. The SPH collimator offers a larger FOV with superior uniformity and noise characteristics compared to the MPH collimator when scanning relatively large radioactivity distributions.

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