

Objective Function,
$$Z = \sum_{m,tm} ObjWt(m, tm) \cdot VM(m, tm) \quad (1)$$

$$\begin{aligned} VM(m, tm) = & \sum_{j,i} VIJ(j, i, m) \cdot INV(j, i, tm) \\ & + \sum_{j,i,t} VPJ(j, m) \cdot P(j, i, t, tm) \\ & + \sum_{r,i,i',t} VQ(r, m) \cdot dist(i, i') \cdot Q(r, i, i', t, tm) \cdot YQ(r, i, i', t, tm) \\ & + \sum_{r,i,t} VI(r, m) \cdot abs(IM(r, i, t, tm)) \cdot YIM(r, i, t, tm), \quad \forall r, m, tm \end{aligned}$$

Constraints:

Technologies balances

$$N(j, i, tm) = N(j, i, tm - 1) + INV(j, i, tm) \quad \forall j, i, tm \quad (2)$$

Flow constraints

$$Q(r, i, i', t, tm) - \frac{Q_{max}}{(PHI(t)/8760)} \cdot YQ(r, i, i', t, tm) \leq 0 \quad \forall r, j, i, t, tm \quad (3)$$

Import/export

$$abs(IM(r, i, t, tm)) - IM_{max} \cdot YIM(r, i, t, tm) \leq 0 \quad \forall r, j, i, t, tm \quad (4)$$

Mass Balance,
$$RS(r, i, t, tm) = \sum_j MU(j, r) \cdot P(j, i, t, tm)$$

$$\begin{aligned} & + \sum_{i'} Q(r, i, i', t, tm) \\ & - \sum_{i'} Q(r, i', i, t, tm) \\ & + IM(r, i, t, tm) \quad \forall r, i, t, tm \end{aligned} \quad (5)$$